YOU-Q

Service Manual

Samm

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1. Introduction

1.1. Scope of this manual

This service manual contains information and instructions about general maintenance and repairs of this electric wheelchair.
This service manual is meant for:

- Service technicians: personnel that performs the regular maintenance and that solves technical problems to the wheelchair.
  Only service technicians that have completed the equipment training for this wheelchair are allowed to do maintenance on this wheelchair.
- Customer support personnel at Handicare BV dealers: personnel that support customers when customers call to the dealer's office with questions about the wheelchair.
  For customer support this manual serves as reference material.

1.2. Reference documentation

This service manual refers, where necessary, to one of the other manuals that are available for this wheelchair.

- User manual wheelchair: for general information about the use of the wheelchair.
- User manual for the electronics: for detailed information about the use of the controller of the wheelchair.
- User manual for the seating system: for detailed information about the user adjustments and the use of the seating system.
- Spare parts manual: for information about the spare parts and their ordering numbers.
- Supplier documentation for the electronics: for detailed information about changing settings and doing repairs on the controls of the wheelchair.

1.3. Symbols used in this manual

This manual uses the following symbols to highlight information that needs extra attention.

WARNING!
Follow the instructions next to this symbol closely.
Not paying careful attention to these instructions could result in physical injury or damage to the wheelchair or to the environment.

NOTICE!
This provides useful background information.

1.4. Guidelines and useful information for maintenance

Service technicians
Maintenance (regular maintenance and repairs) to the wheelchair may only be done by service technicians that have been trained and authorised by Handicare BV. Temporary employees and personnel in training are also allowed to do this work but only under the supervision of an authorised service technician.

Work safely
Always make sure that you work safely, particularly when you need to lift up the wheelchair. During maintenance and repair work you are at all times fully responsible to obey the local applicable guidelines and standards with regard to safety and environment. We advise you

to contact our service department before you do repairs to a wheelchair that has been involved in an accident.
We advise you to disconnect the wheelchair from the battery power, if the wheelchair has to be repaired because of a fault condition. Remove the main fuse(s) while the wheelchair is unattended.

Service and technical support
For information about settings, maintenance and repair works, please contact you supplier.

Make sure you have the following information at hand:
- Type
- Identification number
- Year of manufacture

This information is printed on the identification plate of the wheelchair.

How to order spare parts
For spare parts please use the Spare part manual to see what part numbers you need.

When you order spare parts, please specify:
- Identification number
- Part number
- amount of parts you need
- description (in the relevant language)
- dimensions (if applicable)

Please use e-mail or fax to send your orders to your supplier.

Remarks:
- Parts that do not have a position number cannot be ordered separately. Such parts belong to an assembly that must be ordered and replaced as one piece.
- Boxed position numbers refer to the relevant separate drawing.

Disposal
Always handle waste materials according to the local regulations.

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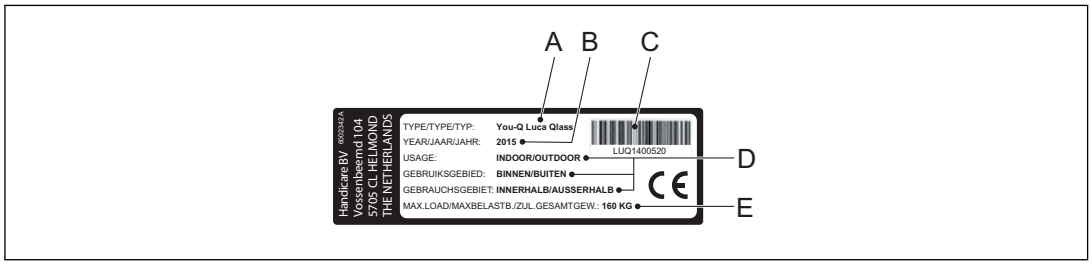
1.5. Product identification



A. Model
B. Year of manufacture
C. Identification number
D. Usage area
E. Maximum load in kg

2. Warranty and Liability

In the following warranty and liabilty stipulations the following terms are used:

- **Product**: the electric wheelchair manufactured Handicare BV.
- **User**: the person who actually uses the product.
- **Customer**: the person who obtains the product from Handicare BV.
- **Dealer**: the person/company who supplies the product from Handicare BV to the customer.

2.1. Warranty

1. Save in so far as the following provisions stipulate otherwise, Handicare BV warrants to the Customer or user of the Product that the Product is sound and fit for the purpose for which the Product is intended to be used – as set forth in the user's manual of the Product. Handicare BV furthermore warrants the quality of the material used to manufacture the Product as well as the quality of the manufacturing process.
2. Handicare BV shall replace parts of the Product which are defective due to faulty materials or manufacturing defects on free of cost basis, provided that such defects arise within one (1) year after the date of delivery of the Product to the Customer. Consequently, the following shall be excluded from the scope of free replacement as meant in the preceding sentence:
   a) replacement of parts of the Product required on account of defects arisen more than one (1) year after the date of delivery of the Product to the Customer;
   b) replacement of parts of the Product required on account of defects resulting due to improper or careless use of the Product or resulting due to using the Product for a purpose other than the intended purpose; if a Dealer is a Customer, this Customer shall save Handicare BV harmless from and against any claims by Users or other third parties for defects resulting due to improper or careless use of the Product;
   c) parts subject to wear and tear, and the repair/replacement of these parts is the result of normal wear and tear;
   d) without prejudice to the provisions of article 2, the warranty with respect to the battery of the electric wheelchair only covers instances of malfunctioning or non-functioning which are evidently the direct result of material defects or manufacturing defects. The warranty as set out in these provisions does not cover a battery which is malfunctioning or non-functioning due to normal wear and tear or due to improper or incompetent use of the Product or the battery forming part of the Product, including the improper charging of the battery and the failure to perform timely and proper maintenance; the Customer shall save Handicare BV harmless from and against any claims by Users or other third parties for defects resulting due to improper or careless use of the Product or the battery forming part thereof. This includes damage resulting due to the leakage of battery acid when performing maintenance to (wet) batteries.
3. The warranties as explained in the preceding provisions shall in any event cease to be effective if:
   a) the Product maintenance guidelines drawn up by Handicare BV have been observed not at all or to an insufficient extent;
   b) repair/replacement of parts results from neglecting, damaging or overburdening the Product or using the Product for purposes other than its intended purpose;
   c) parts of the Product have been replaced by parts not of the same origin as those used by Handicare BV and/or parts of the Product have been replaced without authorisation by Handicare BV
4. The warranties as set forth in articles 1 up to and including article 3 above shall become null and void if the Product is reused by a new User within the warranty period and that reuse necessitated modifications, of whatever kind, to the Product, which modifications were not authorised or performed by and/or on the instructions of Handicare BV
5. The above warranty shall also become null and void if through the agency of the Customer, in instances other than those mentioned in article 4, our Products have been altered in such way as to cause our Products to malfunction.
6. In the event of damage or other calamities the User or the Customer must contact Handicare BV as soon as possible and provide the most extensive information possible if they wish to retain their rights under the warranty set out above. The possibility to lodge a claim under the above warranties shall lapse upon expiry of a period of twenty (20) days after the damage or calamity occasioning the claim arose.
7. The replacement of a part or the repair or reconditioning of the Product during a warranty period shall not extend the warranty period.
8. Any repair to or reconditioning of the Product not authorised or performed by and/or on the instructions of Handicare BV shall not be covered by the scope of this warranty. If a

User has authorised or performed and/or instructed the repair or reconditioning of a Product, the Customer shall save Handicare BV harmless from and against any claims by third parties following – in the widest sense – from such repair or reconditioning.

9. In consideration of the matters considered in the preceding paragraphs of this article 9, the following parts subject to wear and tear or breakage risk shall in any event be excluded from the scope of free repair/replacement unless the breakage and/or wear and tear has been caused by faulty materials and/or manufacturing defects:
   a) foot plates and/or foot rests;
   b) carbon brushes;
   c) upholstery of the seat;
   d) frame covers, rain covers and other covers, apron, winter cover, immobilisation waistcoats, cross straps, sitter's pants and other similar accessories;
   e) tyres;
   f) damage to breakable materials such as lamps and other parts qualifying as vulnerable.
   Depending on the other specifications of the Product, this list may be extended on the basis of a list possibly attached to these terms and conditions (Schedule 1).
10. In the event that a User lodges a claim under a warranty with a Customer or that a Customer lodges such claim, Handicare BV shall be notified immediately.
11. If Handicare BV has determined a claim under the warranty to be justified, the costs of transport to Handicare BV will be borne by the Customer, the costs of transport to the Customer will be borne by Handicare BV

2.2. Liability

1. Subject to the following provisions, Handicare BV only assumes liability for damage arising out of death or bodily injury due to a defect in the Product for which Handicare BV is liable and for damage to another good owned by the User of the Product in a private capacity, provided that such damage is the direct result of a defect in the Product.
2. Handicare BV shall indemnify for damage as referred to in article 1 up to the sum covered by its statutory liability insurance taken out with its insurance company.
3. Handicare BV shall not assume any other or additional liability than the liability set out in article 1. In particular, Handicare BV shall not assume any liability for consequential damage in whatever form.
4. In so far as Handicare BV – notwithstanding the provision of article 3 – is ordered by a Netherlands court or in any other forum for the settlement of disputes to pay damages other than referred to in article 1, Handicare BV shall make indemnification in accordance with the provisions of article 2.
5. Handicare BV shall not assume liability for damage resulting due to repair or replacement required to remedy defects caused by improper or careless use of the Product or caused by modifications made by the Customer or User which were not authorised or performed by and/or on the instructions of Handicare BV
6. The Customer shall save Handicare BV harmless from and against any claims by Users under the warranty provisions referred to in Article 9 or claims for liability under mandatory law if the Customer or third parties have made modifications which are not in accordance with the supplied instructions and/or which have been made using the wrong materials, unless this failure to observe the instructions or use the right materials is based on an error in the technical manual or other instructions imparted by Handicare BV
7. The Customers shall likewise save Handicare BV harmless from any against any liability resulting due to representations made by the Customer with regard to the Product which are incompatible with the quality or the normal use of the Product.

3. Safety

3.1. Personnel qualifications

Only service technicians that are trained and authorised by Handicare BV are allowed to do maintenance and repairs to the wheelchair.
Temporary employees and persons in training are only allowed to do the maintenance and repairs to the wheelchair if they work under the supervision of an authorised service technician.

3.2. Cautions and warning statements

Safety information

- Safety information is indicated with the warning symbol. Wherever possible, safety information is provided in the relevant chapter.

Functionality

- After repairing, reprogramming or replacing parts, always check the functionality of the entire wheelchair. Pay special attention to safety features such as slowdown driving or drive inhibits when seat lift and tilt are both used.

Temperature

- Avoid physical contact with the wheelchair's motors at all times. Physical contact can cause burns. Motors are continuously in motion during use and can reach high temperatures. After use, the motors cool down slowly.
- If the wheelchair is not in use, make sure that it is not exposed to direct sunlight for lengthy periods of time. Some parts of wheelchair, such as the seat, the back and the armrest can become hot if they have been exposed to full sunlight for too long. This may cause burns or allergic reactions to the skin.

Programming

- Programming should only be conducted by healthcare professionals with in-depth knowledge of wheelchair control systems. Incorrect programming could result in an unsafe set-up of the wheelchair for a user. Handicare BV accepts no responsibility for losses of any kind if the programming of the control system is altered without authorization of Handicare BV.

Seat adjustment factory settings
Handicare BV will deliver a wheelchair with default factory settings. These settings depend on the options ordered with the wheelchair. When a configuration is ordered that causes interference, Handicare BV applies modified settings.

Moving parts

- Contact with moving parts of the wheelchair should be avoided. Contact with moving parts can result in serious physical injury or damage to the wheelchair. Pay attention to the following parts:
  - Wheels (drive and castor)
  - Electric tilt in space adjustment
  - Electric high/low option
  - Electric back adjustment
  - Electric legrest

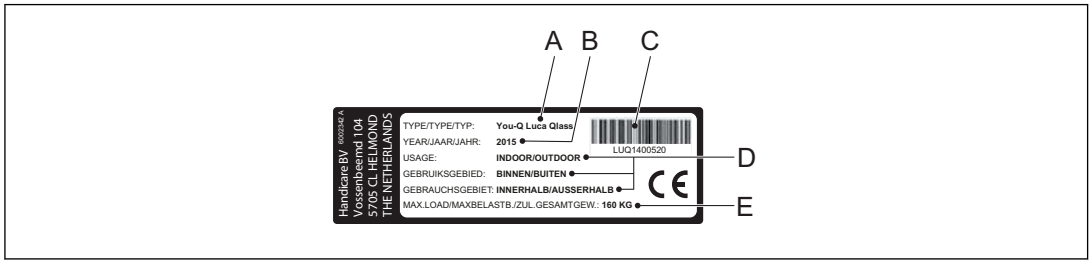
Electromagnetic radiation

The standard version of the electric wheelchair has been tested on the applicable requirements with respect to electromagnetic radiation (EMC requirements). In spite of these tests:

- it cannot be excluded that electromagnetic radiation can have influence on the wheelchair. For example:
  - mobile telephony
  - large scale medical apparatus
  - other sources of electromagnetic radiation
- it cannot be excluded that the wheelchair can interfere with electromagnetic fields. For example:
  - shop doors
  - burglar alarm systems in shops
  - garage door openers

In the unlikely event that such problems occur, contact your supplier immediately.

3.3. Pictograms on the wheelchair



A check manual before using.

B Danger of crushing
Be careful when swinging the controller aside to avoid getting anything crushed.

C Battery charging connection

D Attachment point of the tie down system for transportation on a vehicle.

E Freewheel switch
Do not put the freewheel switch in 'Push' mode on a slope.

F Trap danger
Danger of getting fingers jammed.

G Identification plate

4. Maintenance schedule & tooling

4.1. Overview of scheduled maintenance tasks

No Spares

NOTICE!
The wheelchair must be checked regularly by an authorized service technician.

System Unit	Task	Limit
Batteries	Charging	Daily (by the user)
Tyres	Check pressure and inflate if necessary	Weekly (by the user)
Wheelchair and upholstery	Clean	Weekly (by the user)
Electrical system	Inspection	Twice a year / every 6 months
Batteries	Inspection	Twice a year / every 6 months
Drive	Inspection	Twice a year / every 6 months
Mechanical parts	Inspection	Yearly
Bearings	Inspection	Yearly
Tyres	Check condition and profile	Yearly
Fasteners and bolts	Check condition and tighten if necessary	Yearly
Wheelchair	Check overall functionality	Yearly

4.2. Mechanical tools

The following tools and general supplies are needed to do the maintenance as described in this manual:

Description	Remark
Screwdriver	size: medium
Screwdriver	Phillips head
Rubber mallet	
Pair of wire cutters	
Circlip pliers	
Waterpump pliers	
Open ended spanner	sizes: 10, 13, 17, 19
Ring spanner	sizes: 10, 13, 17, 19
Torque wrench, up to 60 Nm with sockets	sizes: 10, 13, 17, 19
Allen keys	sizes: 3, 4, 5, 6, 7, 8
Loctite 270	for bolt securing
Loctite 648	
Tie wraps	color: black

n/a: not applicable

4.3. Electronical tools

The following tools and general supplies are needed to do the maintenance as described in this manual:

Part number	Description	DX2	DX	Shark	R-Net	VR2
00355.0440	Dynamic Hand Held Programmer (DX-HHP-GDW)	x	x	x		
1003236	Dynamic Wizard USB set OEM (DWIZ-KIT + DWD-OEM-U)	x				
6000668	Dynamic Wizard USB set dealer (DWIZ-KIT + DWD-DLR-U)	x		x	x	
9003295	PGDT R-Net programmer OEM (D50611)				x	
6000614	GDT VR2 PC-Programmer B set (D50145)					x
	Universal meter (voltage and resistance	x	x	x	x	x

4.4. Torque table

Use the general torques as indicated in the table below, unless specified otherwise

Thread Size	Pitch (mm)	Max. torque (Nm)
M4	0.7	3
M5	0.8	6
M6	1	10
M8	1.25	25
M10	1.5	50
M12	1.75	80
M14	2	120

The minimum torque values are 7 - 9 % below the maximum values.

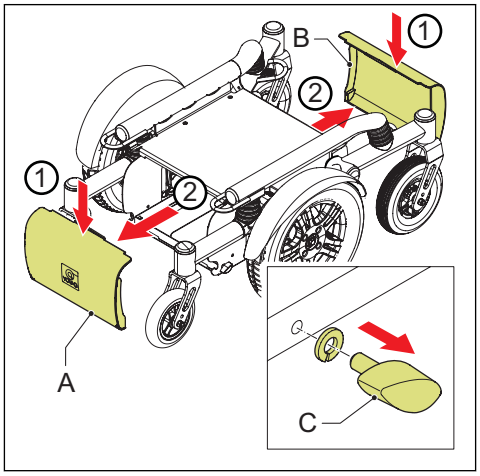
5. Maintenance tasks & adjustments

5.1. General preparations for maintenance

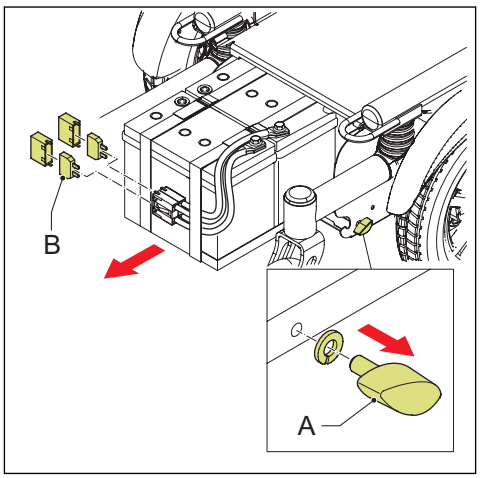
This chapter describes the general preparations that apply for all maintenance and repairs to the wheelchair.

WARNING!
Only do maintenance on an empty wheelchair.

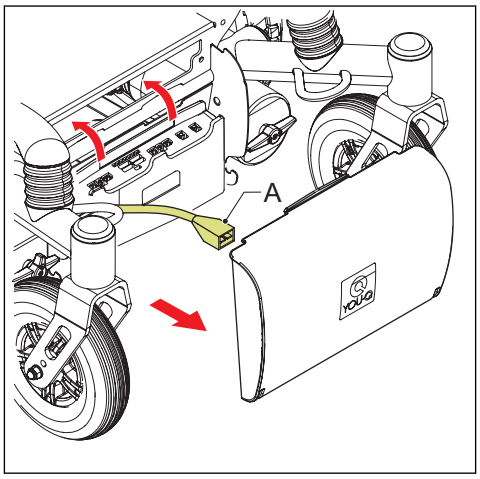
1. Switch off the wheelchair via the button on the controller.
2. Set both freewheel switches in 'Drive' mode.
3. Remove the covers (A and B) as follows:
   - Press down (1) in the middle to the unlock the cover.
   - Remove (2) the cover.



4. Remove the wing bolts (A).
5. Pull the batteries outwards for easy access.
6. Disconnect the batteries by removing the main fuses (B).



7. Disconnect the motor cable (A) from the interconnection of the power module.

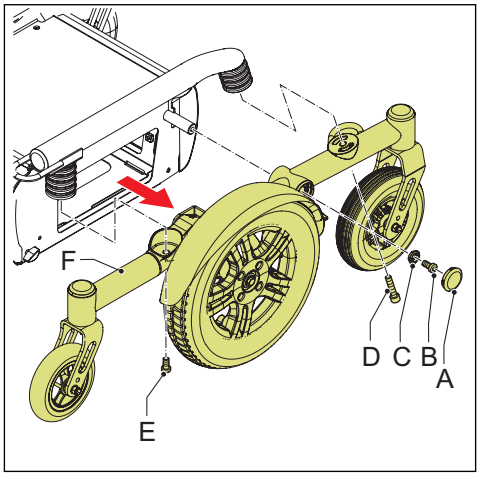


WARNING!
After repairing, reprogramming or replacing parts, always check the functionality of the entire wheelchair. Pay special attention to safety features such as slowdown driving or drive inhibits when seat lift and tilt are both used.

5.2. Carrier

5.2.1. Disassemble a motor arm

Preparation
See section *5.1.*
Procedure
1. Lift the wheelchair until the wheels are free from the floor.
   - Use a lifting platform.
2. Remove cap A.
3. Remove screw B and bearing holder C.
   - Use an allen key size 7.
   - The screw is secured with locking glue.
4. Remove the screws D and E.
5. Hold the motor arm (F) in position and carefully slide it outward.
   - The suspensions are loosely fitted to the carrier frame and may fall off during this procedure. No worries.
6. Take the motor cable out of the carrier.



A number of parts are now accessible for repairs. See the applicable procedure for further instructions.

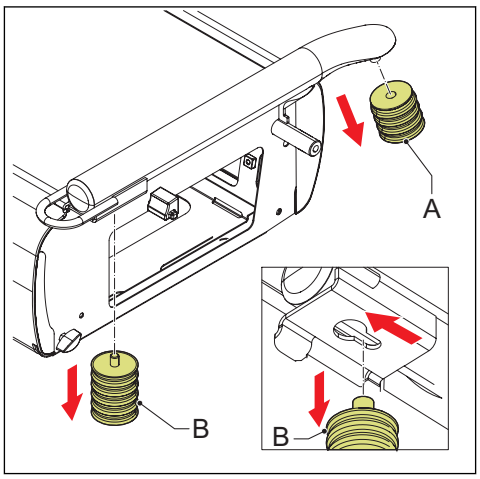
5.2.2. Replace a rubber suspension

NOTICE!
From 1-12-2013 all rubber suspensions have a coloured dot that indicates the hardness:

- Blue (standard): 55 degr. Shore (normally mounted on front side)
- White (hard): 70 degr. Shore (normally mounted on rear side)

Preparation
See section *5.2.1.*
Procedure

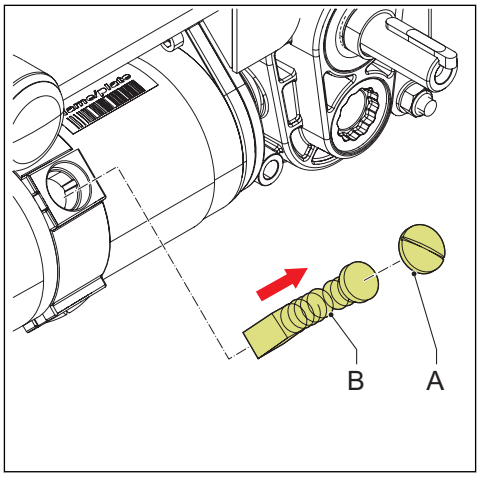
1. Remove the old rubber suspensions (A and B) from the carrier frame.
2. Put the new rubber suspension on the carrier frame.
3. Install the motor arm on the wheelchair. See section *5.2.5.*



5.2.3. Replace the carbon brushes

Preparation
See section *5.2.1.*
Procedure

1. Remove the cap (A).
2. Remove the old carbon brush (B).
3. Gently blow some air through the hole (to remove any dust).
4. Put the new carbon brush in the motor.
5. Put the cap on the motor.
6. Repeat steps 1 through 5 for all the carbon brushes on the motor.
7. Mount the motor arm on the wheelchair. See section *5.2.5.*



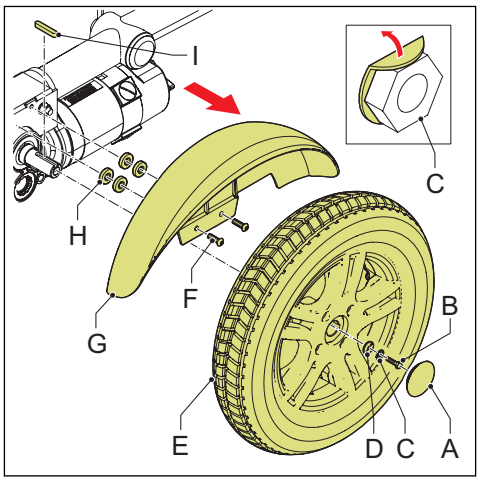
5.2.4. Replace a drive motor

Preparation

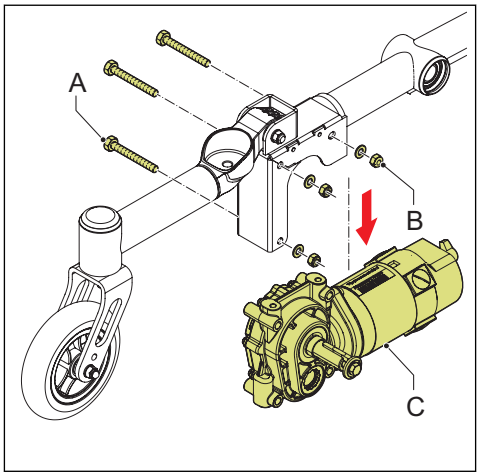
See section *5.2.1.*

Procedure

1. Remove cap A.
2. Unfold the washer (C).
3. Remove screw B and washer D.
4. Remove the drive wheel (E) from the motor axle.
   - Make sure that you do not loose the key (I).
5. Remove the mudguard (G) for easy access.

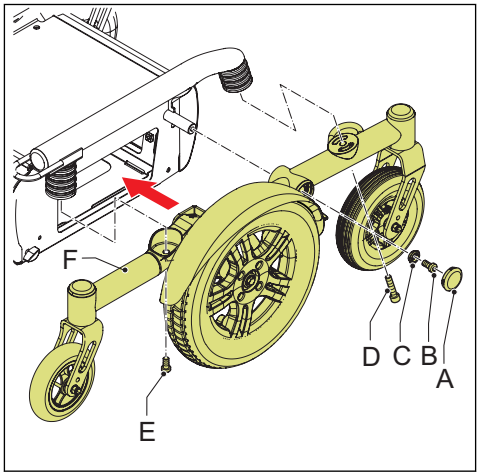


6. Remove the old drive motor (C)
   The screws (A) and nuts (B) can be discarded.
7. Install the new motor.
   Use the screws and nuts that are enclosed with the new motor.
8. Install the mudguard.
9. Install the drive wheel.
   a. Put some grease on the axle to prevent fretting.
   b. Mount the drive wheel on the axle.
   c. Make sure to lock the nut by folding the washer.
10. Make sure that the drive wheel does not interfere with the motor.
11. Install the motor arm on the wheelchair. See section *5.2.5.*



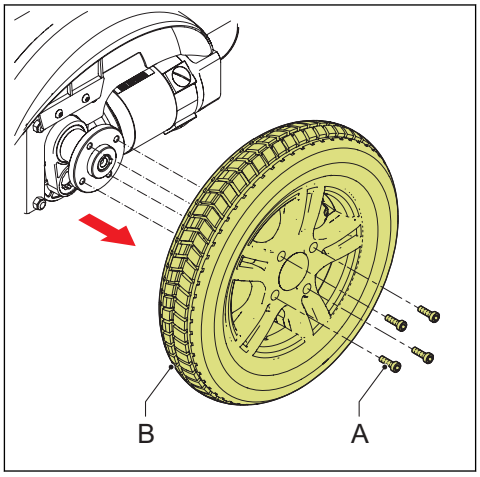
5.2.5. Install a motor arm

Preparation
Make sure that the rubber suspensions are installed on the carrier.
Procedure
1. Put the motor cable through the carrier.
   Do not connect it yet.
2. Hold the motor arm (F) and carefully slide it inward on the carrier.
   - Make sure that the rubber suspensions fit into their locations on the motor arm.
3. Fasten the motor arm to the carrier frame (with items A -C).
   Use some Loctite 648 to secure the screw B.
4. Fasten the suspensions (with items D and E).
5. Connect the motor cable to the interconnection of the power module.



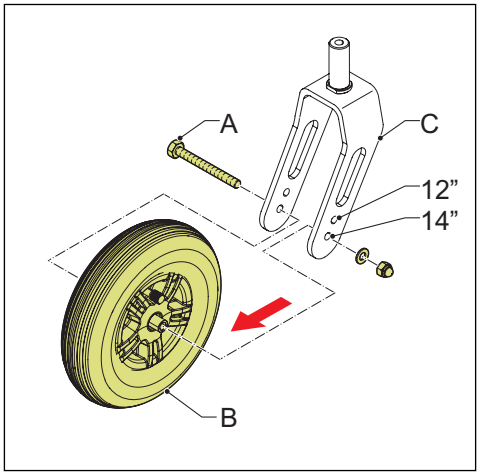
5.2.6. Replace a drive wheel

Preparation
See section *5.1.*
Procedure
1. Lift the wheelchair until the wheels are free from the floor.
   - Use a lifting platform.
2. Remove the screws (A).
3. Remove the old drive wheel (B).
4. Install the new drive wheel.
5. Make sure that the drive wheel does not interfere with the motor.



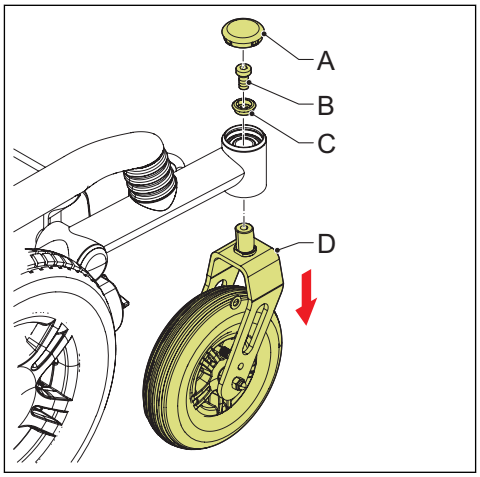
5.2.7. Replace a castor wheel

Preparation
See section *5.1.*
Procedure
1. Lift the wheelchair until the wheels are free from the floor.
   - Use a lifting platform.
2. Remove screw, washer and nut A.
3. Take out the old castor wheel (B) from the fork (C).
4. Install the new castor wheel.
   - The position of the wheel depends on the size of the drive wheel: 12" or 14".
   - Use a new lock nut.



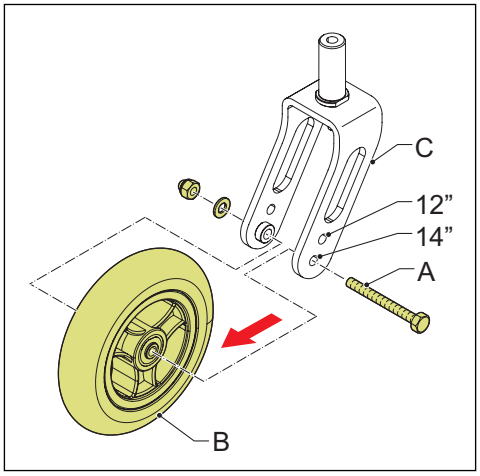
5.2.8. Replace a castor fork

Preparation
See section *5.1.*
Procedure
1. Lift the wheelchair until the wheels are free from the floor.
   - Use a lifting platform.
2. Remove cap A.
3. Remove screw B and bearing holder C.
   - Use an allen key size 7.
   - The screw is secured.
4. Remove the old castor fork (D) from the carrier frame.
5. Install the new castor fork on the carrier frame.
   - Use some Loctite 648 to secure the screw B.



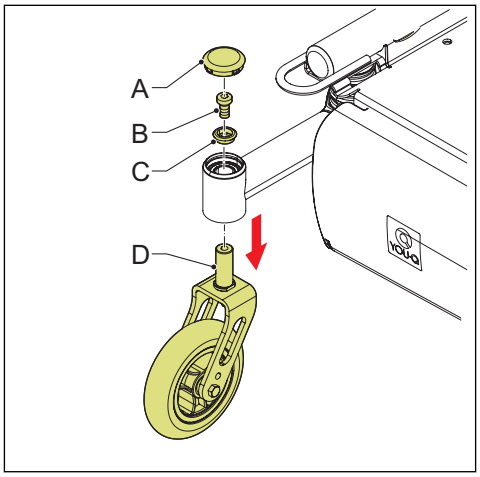
5.2.9. Replace an anti-tip wheel

Preparation
See section *5.1.*
Procedure
1. Lift the wheelchair until the wheels are free from the floor.
   - Use a lifting platform.
2. Remove screw, washer and nut A.
3. Take out the old anti-tip wheel (B) from the fork (C).
4. Install the new anti-tip wheel.
   - The position of the wheel depends on the size of the drive wheel: 12" or 14".
   - Use a new lock nut.



5.2.10. Replace an anti-tip fork

Preparation
See section *5.1.*
Procedure
1. Lift the wheelchair until the wheels are free from the floor.
   - Use a lifting platform.
2. Remove cap A.
3. Remove screw B and bearing holder C.
   - Use an allen key size 7.
   - The screw is secured.
4. Remove the old anti-tip fork (D) from the carrier frame.
5. Install the new anti-tip fork on the carrier frame.
   - Use some Loctite 648 to secure the screw B.



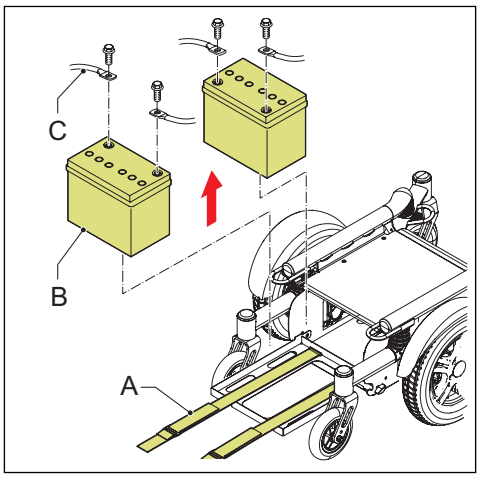
5.2.11. Replace the batteries

Preparation
See section *5.1.*
Procedure
1. Loosen the battery straps (A).
2. Disconnect the power cables (C).
3. Remove the old batteries (B).
4. Put the new batteries in the carrier.
5. Connect the power cables.

WARNING!
See the 'cables and module schemes' in section *8.*

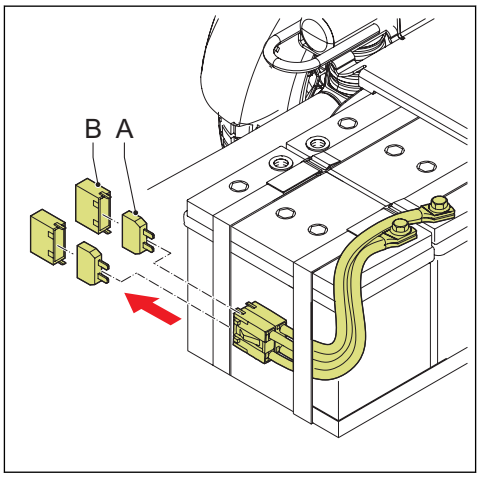
6. Tighten the battery straps and make sure that the power cables are properly placed underneath the battery straps.

WARNING!
Make sure that the battery straps are tight.



5.2.12. Replace main fuse

Preparation
See section *5.1.*
Procedure
1. Remove the caps (B) and the old fuses (A).
2. Put the new fuses in the fuse holders and put the caps on the fuse holders



5.3. Interface (all types)

5.3.1. Adjust the position of the interface

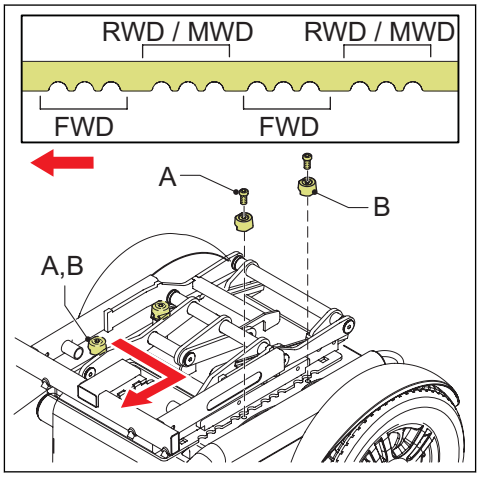
The position of the interface can be adjusted in order to give the wheelchair better driving characteristics. This position depends on the seat depth (as set on the seating system) and the drive type (front wheel drive, mid wheel drive or rear wheel drive).
Preparation
1. Set the interface in the maximum tilted position for easy access.
2. Switch off the wheelchair via the button on the controller.
3. Set both freewheel switches in 'Drive' mode.

4. Disconnect the interface cables from the controller.

Procedure

1. Loosen the screws A (4x).
2. Remove the screws (A) and mounting blocks (C) on one side of the wheelchair.
3. Move the interface to the desired new position.

WARNING!
Only use the positions that match the drive type (RWD: Rear wheel drive, MWD: Mid wheel drive, FWD: Front wheel drive).



4. Put back the mounting blocks and screws that you removed earlier.
5. Make sure that the interface is firmly locked by the mounting blocks and fasten the screws (A).
6. Check if the wheelchair is stable in all available positions for seat lift and tilt.

5.3.2. Adjust the base height of the interface

The height of the interface can be adjusted in order to achieve the seat height as required for the user.

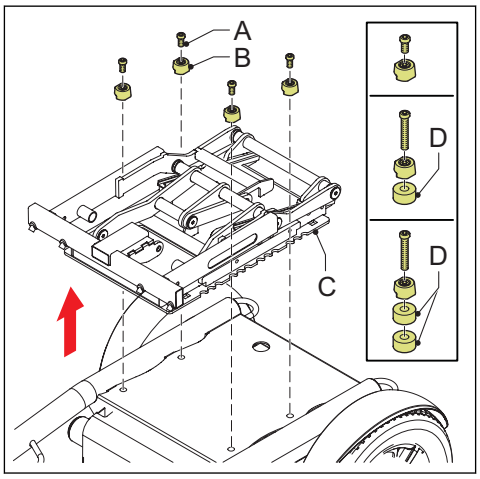
Preparation

1. Set the interface in the maximum tilted position for easy access.
2. Prepare the wheelchair for maintenance. See section *5.1.*
3. Disconnect the interface cables from the controller.

Procedure

1. Remove the screws (A) and mounting blocks (B).
2. Set the required height.
   - Maximum heigth is 5 cm.
   - Do not use more than two spacer blocks (D) per location.
   - Make sure that you use the correct screw length.

WARNING!
Only use spacer blocks that are supplied by YOU-Q and obey the maximum heigth. Other spacer blocks or height can make the wheelchair unstable.



3. Make sure that the interface is firmly locked by the mounting blocks and fasten the screws (A).
4. Check if the wheelchair is stable in all available positions for seat and tilt.

5.4. Tilt-only interface

5.4.1. Replace the Tilt Actuator (Tilt-only Interface)

Preparation

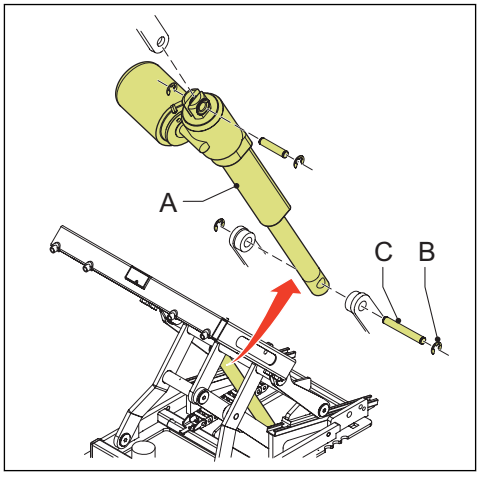
1. Set the interface in the maximum tilted position for easy access.
2. Prepare the wheelchair for maintenance. See section *5.1.*
3. Disconnect the interface cables from the controller.

Procedure

1. Make sure that the interface is kept in the tilted position. For instance by placing a support.
2. Disconnect the actuator cable.
3. Remove the circlips (B) from the pivot (C) at both ends of the actuator (A).
4.

WARNING!
Make sure that the tilt mechanism is supported safely.

Remove the old actuator.
5. Put the new actuator into the tilt mechanism.
6. Connect the actuator cable.
7. Make sure that the actuator cable can follow the movement of the mechanism but that the cable does not get jammed by the mechanism.
8. Check the functionality of the actuator.



5.5. Tilt + lift interface

5.5.1. Replace the tilt actuator

Preparation

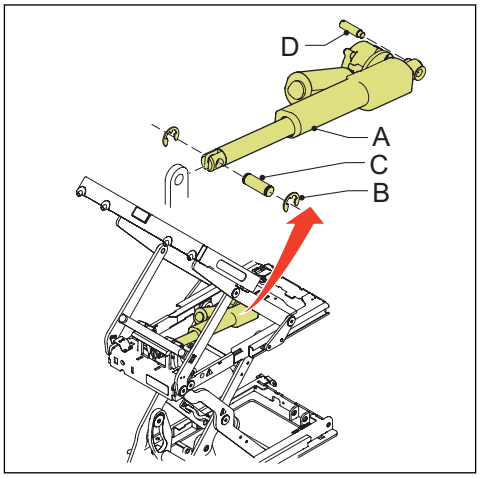
1. Set the interface in the maximum tilted position for easy access.
2. Prepare the wheelchair for maintenance. See section *5.1.*
3. Disconnect the interface cables from the controller.

Procedure

1. Make sure that the interface is kept in the tilted position. For instance by placing a support.
2. Disconnect the actuator cable.
3.

WARNING!
Make sure that the tilt mechanism is supported safely.

Remove the circlips (B) at the pivot (C) at the end of the actuator.
4. Remove the old actuator (A).
5. Put the new actuator into the tilt mechanism.
6. Connect the actuator cable.
7. Make sure that the actuator cable can follow the movement of the mechanism but that



the cable does not get jammed by the mechanism.
8. Check the functionality of the actuator.

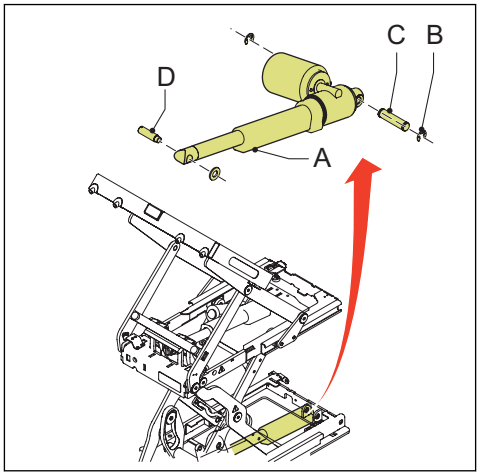
5.5.2. Replace lift actuator

Preparation
1. Set the interface in the maximum lift position for easy access.
2. Prepare the wheelchair for maintenance. See section *5.1.*
3. Disconnect the interface cables from the controller.

Procedure
1. Make sure that the interface is kept in the upper position. For instance by placing a support.
2. Disconnect the actuator cable.
3.

WARNING!
Make sure that the lift mechanism is supported safely.

Remove the circlips (B) from the pivots (C and D).
4. Remove the old actuator (A).
5. Put the new actuator into the tilt mechanism.
6. Connect the actuator cable.
7. Make sure that the actuator cable can follow the movement of the mechanism but that the cable does not get jammed by the mechanism.
8. Check the functionality of the actuator.

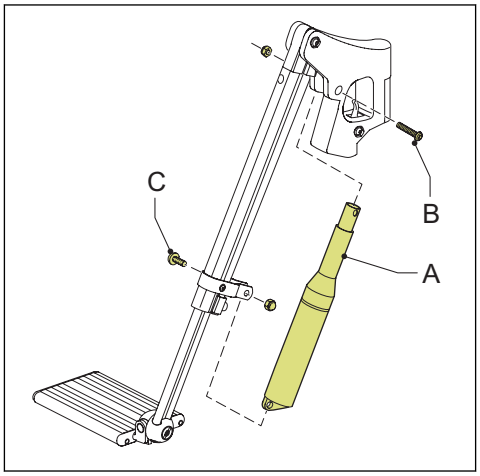


5.6. Legrests

5.6.1. Replace the actuator of a powered Legrest

Preparation
1. Lift the legrest out of the wheelchair.

Procedure
1. Remove the tie wraps and disconnect the actuator cable from the legrest.
2. Remove the screws and nuts (B and C).
3. Remove the old actuator (A) from the legrest.
4. Put the new actuator in the legrest.
5. Connect the actuator cable to the legrest.
6. Put the connector cable into the groove of the legrest and fasten the connector cable with tie wraps.
Make sure that you leave enough free cable length to let the actuator reach its full length.
7. Check the functionality of the actuator.



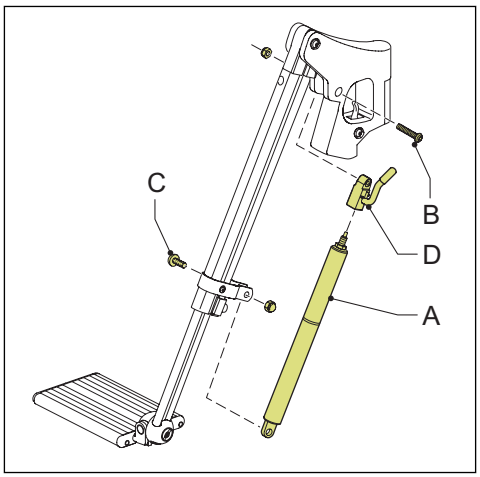
5.6.2. Replace the gasspring of a comfort legrest

Preparation

1. Lift the legrest out of the wheelchair.

Procedure

1. Remove the screws and nuts (B and C).
2. Remove the old actuator (A) from the legrest.
3. Remove the lever block (D) from the gasspring (A). The lever block is re-used with the new gasspring.
4. Put the level block on the new gasspring.
5. Put the new actuator in the legrest.
6. Check the functionality of the actuator.



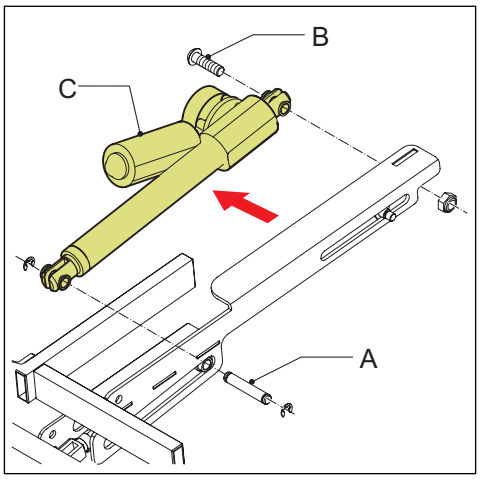
5.6.3. Replace the actuator of the central legrest

Preparation

See section *5.1.*

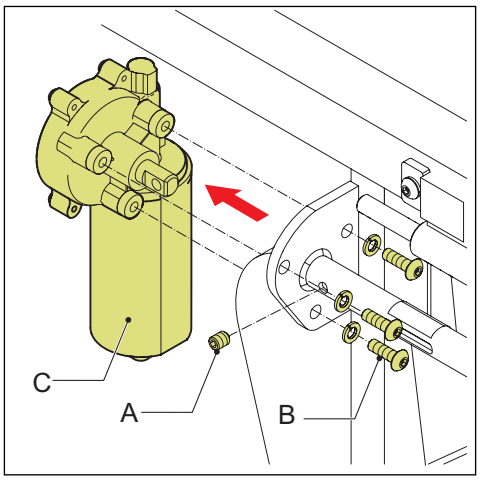
Procedure

1. Remove the seat cushion for easy access.
2. Disconnect the actuator cable.
3. Remove the circlips from the pivot (A).
4. Remove the screw (B).
5. Remove the old actuator (C).
6. Put the new actuator into the wheelchair.
7. Connect the actuator cable.
8. Make sure that the actuator cable is properly arranged. Use tie wraps.
9. Put the seat cushion in the wheelchair.
10. Check the functionality of the actuator.



5.6.4. Replace the motor of the central legrest

Preparation
See section *5.1.*
Procedure
1. Remove the seat cushion for easy access.
2. Disconnect the motor cable.
3. Loosen the locking screw (A).
4. Remove the old motor (C) from the legrest by removing screws B.
5. Put the new motor in the legrest.
6. Fasten the locking screw.
7. Connect the motor cable.
8. Make sure that the motor cable is properly arranged. Use tie wraps.
9. Put the seat cushion in the wheelchair.
10. Check the functionality of the actuator.



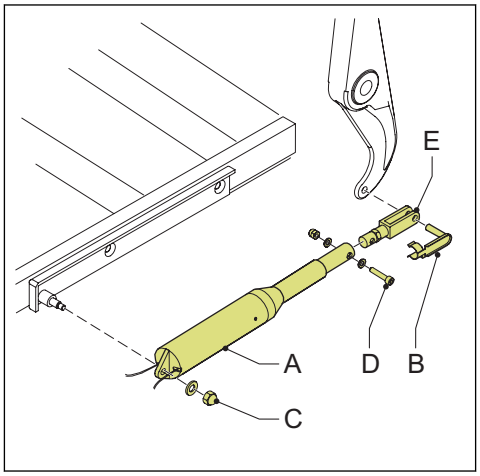
5.7. Seating system

5.7.1. Replace the actuator of the backrest

Preparation
See section *5.1.*
Procedure
1. Remove the seat cushion for easy access.
2. Make sure that the backrest is kept in the upright position. For instance by placing a support.
3. Disconnect the actuator cable.
4.

WARNING!
Make sure that the backrest is supported safely to prevent it from falling backwards.

Remove the mounting clip (B).
5. Remove the nut (C).
6. Remove the old actuator (A).
7. Remove screw, washers and nut (D).
8. Remove the mounting fork from the actuator. The mounting fork is re-used with the new actuator.
9. Put the mounting fork on the new actuator.
10. Put the new actuator into the seating mechanism. Use a new lock nut (C) and fasten the mounting clip (B).



WARNING!
Make sure that the mounting clip (B) is correctly locked on the actuator. This prevents the clip from loosening which in turn might cause the backrest to fall backwards.

11. Connect the actuator cable.
12. Make sure that the actuator cable is properly arranged on the seating system.
13. Check the functionality of the actuator.
14. Put the seat cushion on the wheelchair.

6. Maintenance on the control system

6.1. Replace the remote control (Shark, VR2 and R-Net)

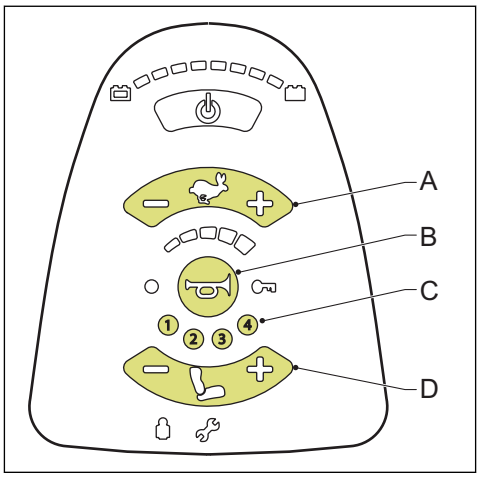
The driving program of the Shark, VR2 and R-Net controller systems is stored in the power module. Replacing the remote control can therefore be done without any programming.

1. Replace the remote control.

6.2. Replace the remote control (DX2)

The DX2 system has the main driving program stored in the remote and a backup of the program in the power module. Replacing the remote can be done without programming.

For REM420:



1. Switch on the controls.
   The actuator LEDs 1 and 4 flash (C). This indicates that the remote control and the power module have different programs.
2. Replace the remote control.
3. Press the "-" button on the actuator selecton bar (D).
   This way you select the backup program from the power module.
4. Simultaneously press the horn button (B) and the "+" button on the drive profile selection bar (A) for 3 seconds.
   This confirms the selection and the system will beep when confirmed.
5. Switch the controls off and on again to activate the new settings.

For REM550:

1. Replace the remote control.
2. Switch on the controls.
   The display shows a selection sequence for the backup program.
3. Replace the remote control.
4. Select the module that has NOT been replaced.
   The backup program from this module will be used to automatically re-programm the new module.

6.3. Replace the power module (Shark, VR2 and R-Net)

The driving program of the Shark, VR2 and R-Net controller systems is stored in the power module.

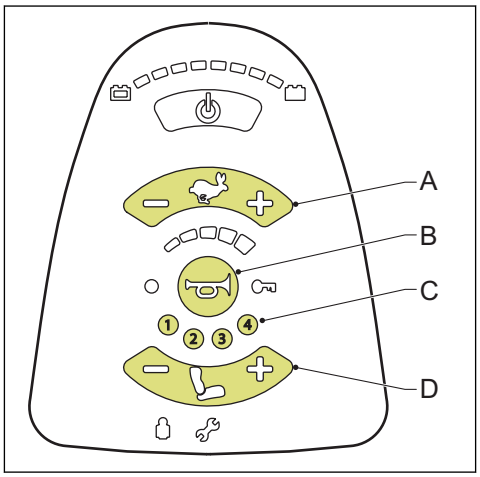
1. Make a backup of the driving program from the power module.
   Use a laptop and programming software for this step.
2. Replace the power module.
3. Load the backup of the driving program in to the new power module.
4. Check all functionality of the wheelchair.

6.4. Replace the power module (DX2)

The DX2 system has the main driving program stored in the remote and a backup of the program in the power module. Replacing the power module can be done without programming.

For REM420:

1. Replace the power module.
2. Switch on the controls.
   The actuator LEDs 1 and 4 flash (C). This indicates that the remote control and the power module have different programs.
3. Press the "+" button on the actuator selection bar (D).
   This way you select the backup program from the remote control.
4. Simultaneously press the horn button (B) and the "+" button on the drive profile selection bar (A) for 3 seconds.
   This confirms the selection and the system will beep when confirmed.
5. Switch the controls off and on again to activate the new settings.



For REM550:

1. Replace the remote control.
2. Switch on the controls.
   The display shows a selection sequence for the backup program.
3. Replace the remote control.
4. Select the module that has NOT been replaced.
   The backup program from this module will be used to automatically re-program the new module.

7. Troubleshooting

This chapter contains table with troubleshooting information. One table shows the troubleshooting for the wheelchair in general, the other tables show information about troubleshooting for the available controls systems.

NOTICE!
If the problem is not solved with the help of the solutions in the tables, contact your dealer/distributor or the Service Department of Handicare BV.

7.1. General diagnostics and faultfinding

Problem	Cause	Solution
Wheelchair does not switch on	Buscables not connected	Check buscable connections of the joystick module to the power module (can also be through the actuator module!)
	Pins in connectors are loose or damaged	Check connectors for loose or damaged pins. If damaged replace cable.
	Buscable defect	Check all bus cables for damage. Bypass each buscable with new one to check functionallity.
	Fuse defect / Thermal trip	Check fuses and replace if needed.
	Battery connections are loose	Check battery connections and restore if needed.
	Battery voltage too low	Measure battery voltage and charge batteries.
	Battery defect	Measure battery voltage. Voltage below 10 V can indicate that one battery is defect. Replace batteries.
	Remote control or button defect	Check by replacing with new one.
	Power Module defect	Check by replacing with new one.
Wheelchair continuously drives slower than normal	Speed limit due to microswitch signal from seating function.	Check if all seating options are in neutral position.
		Measure resistance from the speed limit cable in different seating positions. Bad cable connections or a broken resistor influences the drive inhibit signal.
	Incorrect programming	Check for correct program. Re-program if needed.

Problem	Cause	Solution
	Parking brake partially engaged	Check parking brake function. Clicking sound at engaging/disengaging should be present. Check temperature of parking brake after driving.
Wheelchair drives slower throughout the day (or after several hours)	Poor batteries	Check batteries and battery voltage.
	Poor or incomplete battery charging	Check battery charger. Check charging duration with the user.
	Thermal rollback (overheating)	Check usage of wheelchair, extreme usage can cause the power module to decrease the maximum currents for protection. Check wheelchair in freewheel mode for extreme resistance on rolling or turning.
	(DX2 controls only) Gyro module (if present) is not connected correctly or is not functioning properly => Controllers switch to *SystemSlowDown* mode.	Check Gyro cabling and/or replace Gyro module.
Wheelchair only drives well for a short period of time.	Current limit is set too low or the controller is underspecified	Check program settings and/or replace controller.
Wheelchair can be powered up, but does not drive.	Parking brakes are in freewheel mode (flash code on remote!)	Set parking brakes to Drive mode.
	Drive inhibits active (flash code on remote)	Check program which Drive inhibits are present. Check cabling of Drive inhibits on wheelchair.
Wheelchair has too little power to drive properly	Tyre pressure of drive wheels or castors is too low	Check pressure and inflate if needed. See User manual for correct value.
	Programming of speed and Torque Settings is not correct	Check programming and make corrections if needed.

Problem	Cause	Solution
	Programming of Motor Load Compensation is not correct	Check programming and make corrections if needed. Check with manufacturer for correct value.
Wheelchair veers to one side	Programming of Load Compensation is not correct.	Check programming and make corrections if needed.
	Motors are not "balanced"	Check motor rpm. See motor label for correct value.
	Tyre pressure or tyre size left and right are different	Check tyre pressure and tyre size (diameter).
	Suspension "hardness" left and right are different.	Check suspensions and make sure left and right side have identical suspension rates.
	Carrier is not "in balance" due to mechanical flaws	Check for loose bolts, cracked or worn frame parts. Check height of carrier left and right.
	User weight is not in the center of the wheelchair	Check position of user, see if position can be improved. If not possible use veer compensation in program to correct the steering.
	Chair stops intermittently	High Voltage due to overcharging or driving down slopes with full batteries (regenerative braking). Check battery voltage, drive down slope at lower speed.
	Worn carbon brushes	Check brushes, replace if needed.
	Speed Limit due to micro switch	Check functioning of micro-switch. Due to vibrations or shocks it can temporarily switch to Slowdown mode.
Castor wheels "wobble" at higher speed	Tyre pressure too high.	Check tyre pressure and decrease if needed. See user manual for correct value.
	Too little load on the castor wheels.	Modify seating setup if possible or decrease tyre pressure.

Problem	Cause	Solution
Motors make excessive noise	Worn carbon brushes	Check carbon brushes and collector. If needed replace brushes or motor.
Wheelchair wobbles overall or moves up and down when driving	Drive wheels have radial misaligned tyres. Can be caused by long (weeks) inactive periods	Check for misalignment of tyres. If misaligned, reduce tyre pressure to 1 bar, drive for several minutes at moderate speed and increase pressure again to advised value. Misalignment can be reduced this way. If not sufficient replace wheel.
Seating actuator does not function	Current setting is not correct	Check programming and make corrections if needed. Contact manufacturer for correct settings.
	Cables not connected or cables damaged	Check cables and replace if needed.
	Wheelchair goes into fault status when actuator is operated	Actuator has a short circuit that becomes active when the actuator is operated. Replace actuator.
	Actuator inhibit is active	Check program to see what actuator inhibit is present. Check if inhibit signal is functioning correctly. (example : with lift and tilt to maximum, recline will no longer move backwards.
	Actuator module (output) fault	Try actuators on different output channel to check what output channel has a fault.
Seating actuator only functions for a short time	Maximum current setting is too low	Check programming and make corrections if needed. Contact manufacturer for correct settings.
	Actuator time out setting is too short (or actuator speed is too low)	Check programming and make corrections if needed. Contact manufacturer for correct settings.
	Actuator is internally not functioning properly	Check actuator temperature after operation and/or check for excessive noise when operated. Replace actuator.

Problem	Cause	Solution
	Seating mechanism is moving poorly or with extreme friction	Check mechanisme on loose bolts, cracked or bent parts. Replace parts or modules.
Seating actuator moves in wrong direction (after replacement)	Wiring connections possibly twisted in cable or motor	Change actuator direction in driving program or replace cable or part.
Lighting does not function	Cabling not (correctly) connected	Check cabling. See wiring diagrams for correct connections.
	Lighting settings not correctly set in program	Check programming and make corrections if needed.
Wheelchair moves/turns very slowly and seems to be lacking power	Load compensation too low, incorrect setting.	Modify load compensation in driving program. Check with manufacturer for correct settings.
	Too much load on front castors (RWD).	Modify seating setup to have better weight distribution.
Wheelchair moves very rapidly and jerky	Load compensation is too high.	Modify load compensation in driving program. Check with manufacturer for correct settings.

7.2. Diagnostics and troubleshooting for Shark controls

WARNING!
Remove both fuses from the batteries before you change any cables, fuses and/or modules. This way the power way is disconnected from the wheelchair.

NOTICE!
For more detailed information about Shark Controllers, specific manuals can be downloaded from the website: www.dynamiccontrols.com.

Problem	Cause	Solution
Service indicator flashes once	User error. This is probably a 'STALL' timeout.	Put the joystick in neutral and try again.
Service indicator flashes twice	Battery fault.	Check batteries and cabling. Charge the batteries or replace them.
The ON-OFF light flashes 3 times.	The left-hand motor (m1) connection is not good.	Check the connection and the cabling.
	The left-hand motor (m1) is defect.	Replace this motor.
The ON-OFF light flashes 4 times.	The right-hand motor (m2) connection is not good.	Check the connection and the cabling.
	The m2 motor is defect.	Replace this motor
The ON-OFF light flashes 5 times	The left-hand parking brake (m1) connection is not good or disconnected.	Check the connection and the cabling.
	The left-hand parking brake (m1) is defect.	Replace this motor.
The ON-OFF light flashes 6 times	The right-hand parking brake (m2) connection is not good or disconnected.	Check the connection and the cabling.
	The right-hand parking brake (m2) is defect.	Replace this motor.
The ON-OFF light flashes 7 times	Controller fault	Check all connections and correct them if needed. If the fault signal is still present after this, replace the controller.
The ON-OFF light flashes 8 times	Power module fault	Check all connections and correct them if needed. If the fault signal is still present after this, replace the power module.
The ON-OFF light flashes 9 times	Communication fault in the Shark system	Check all connections and correct them if needed. If the fault signal is still present after this, replace the controller.

Problem	Cause	Solution
The ON-OFF light flashes 10 times	Unknown fault	Check all connections and correct them if needed. If the fault signal is still present after this, contact the Service Department of Handicare BV.
The ON-OFF light flashes 11 times	System does not 'fit'. System modules are not compatible.	Check if the controller type corresponds with the power module. Replace one of the two if needed.

7.3. Diagnostics and troubleshooting for DX2 controls

WARNING!
Remove both fuses from the batteries before you change any cables, fuses and/or modules. This way the power is disconnected from the wheelchair.

NOTICE!
For more detailed information about DX2 Controllers, specific manuals can be downloaded from the website: www.dynamiccontrols.com.

Problem	Cause	Solution
ON-OFF light does not go on; wheel and does not move	Controller plug not properly connected to the power module.	Check the connection.
	Both fuses are defect	Replace fuses.
	The batteries are not properly connected.	Check the connection.
ON-OFF light flashes once	DX module defect	Replace one or more modules. The ON-OFF LED shows the condition of the system. All modules have a separate status LED, in this way you can see which one is defect.
ON-OFF light flashes twice	DX accessory defect.	The module shows a fault as a result of a programming fault, or short circuit and/or overload of the accessories. The (optional) electrical high/low adjustment is not in the lowest position. De LED flashes twice to indicate that the speed limitation has been switched on; the wheelchair will drive considerably slower.
The ON-OFF light flashes 3 times.	The left-hand motor (m1) connection is not good (loose or short circuit)	Check the connection and the cabling.
	The left-hand motor (m1) connection is defect	Replace the motor.
	Output of the power module is defect	Check the motor; an output of the power module will only become defective through a defect in the motor itself. Only replace the power module if the error occurs immediately when you switch on the power module. If the error occurs when you start to drive, the entire motor circuit causes this error. In this case, replace the motor.

Problem	Cause	Solution
The ON-OFF light flashes 4 times.	The right-hand motor (m2) connection is not good (loose or short circuit)	Check the connection and the cabling.
	The right-hand motor (m2) connection is defect	Replace the motor.
	Output of the power module is defect	Check the motor; an output of the power module will only become defective through a defect in the motor itself. Only replace the power module if the error occurs immediately when you switch on the power module. If the error occurs when you start to drive, the entire motor circuit causes this error. In this case, replace the motor.
The ON-OFF light flashes 5 times	The left-hand parking brake (m1) connection is not good or disconnected.	Check the connection and the cabling.
	The left-hand parking brake (m1) is defect.	Replace the drive motor.
The ON-OFF light flashes 6 times	The right-hand parking brake (m2) connection is not good or disconnected.	Check the connection and the cabling.
	The right-hand parking brake (m2) is defect.	Replace this drive motor.
The ON-OFF light flashes 7 times	The battery voltage is low, or the batteries are flat or bad	Charge the batteries or replace them. **NOTE:** If the voltage is low (<12 V) the electronics do not work properly. A number of random LEDs of the DX controller flash and the wheelchair will not function.
The ON-OFF light flashes 8 times	The battery voltage is high: above 32 V	This usually occurs during (trickle) charging. Frequent occurrences will result in a defective power module. Correct the charger settings.

Problem	Cause	Solution
The ON-OFF light flashes 9 times	'BUS low' error: cable breakage in (one of the DX BUS cables) or short circuit in the DX BUS system (entrance to the modules)	Check all cables and module and replace them if needed.
The ON-OFF light flashes 10 times	'BUS high' error: usually a communication error is caused by one of the DX BUS cables or DX modules (entrance to the modules)	Check all cables and module and replace them if needed. If the fault signal is still present after this, contact the Service Department of Handicare BV.
The ON-OFF light flashes 11 times	'STALL' overload error: a motor continuously demands too much power.	Check the drive units. **Note:** This error is often caused by taking obstacles that are too high, or by driving against walls, and door frames etc. This error may also be caused by a difficult turn from a standing position. Check the weight distribution of the wheelchair.
The ON-OFF light flashes 11 times	System does not 'fit'. System modules are not compatible.	Program the entire drive system for the relevant wheelchair with the aid of the DX-Wizard program on the PC. Always confirm the programming by switching the wheelchair on and off.

7.4. Diagnostics and troubleshooting for R-Net controls

WARNING!
Remove both fuses from the batteries before you change any cables, fuses and/or modules. This way the power is disconnected from the wheelchair.

NOTICE!
For more detailed information about R-Net Controllers, specific manuals can be downloaded from the website: www.pgdt.com.

Trip Text	Trip code	Description
Joystick error	-	The most common cause of this error is when the joystick is not in the center position when the control system is switched on. The *Joystick displaced* screen is shown for 5 seconds. If the joystick is not released within this time, the system reports an error. • Make sure that the joystick is in the center position and re-try to switch on the system. If the error is still present: the joystick or the joystick module may need to be replaced.
Low Battery	-	The control system detects that the battery voltage is below 16V. • Check the condition of the batteries and check the connections to the control system. If this does not solve the error, the power module may be defect.
High Battery	-	The control system detects that the battery voltage is above 35 V. Most common reasons for this are: overcharging of the batteries or bad connections between the batteries and the control system. • Check the condition of the batteries and check the connections to the control system. If this does not solve the error, the power module may be defect.
M1 Brake Error	1505	The control system detects a problem in the solenoid brakes of the M1 motor or the connection to them. • Check the solenoid brakes, cables and the connections to the control system. If this does not solve the error, the power module may be defect.
M2 Brake Error	1506	The control system detects a problem in the solenoid brakes of the M2 motor or the connection to them. • Check the solenoid brakes, cables and the connections to the control system. If this does not solve the error, the power module may be defect.
M1 Motor Error	3B00	The control system detects that this motor has become disconnected. • Check the motor, cables and the connections to the control system. . If this does not solve the error, the power module may be defect

Trip Text	Trip code	Description
M2 Motor Error	3C00	The control system detects that this motor has become disconnected. • Check the motor, cables and the connections to the control system. If this does not solve the error, the power module may be defect.
Inhibit Active	1E01 1E09 1E0A	One of the inhibit input is active and in a latched state. The active inhibit is indicated by the last 2 digits of the trip code. • Turn the power off and on. This will drop out of the Latched Mode which might clear the trip. • Check all cables and switches that are connected to the active inhibit. If this does not solve the error, the ISM may be defect.
Joystick Calibration Error	-	The Calibration of the joystick has not been successful. • Enter OBP and re-try to calibrate. If this does not solve the error, the joystick module may be defect.
Memory Error	-	This is a non-specific memory error which can be caused by any of the modules within the system. • Check all cables and connections. • Turn the power off and on. If the error is still present and the system contains modules not supplies by PGDT: • Disconnect all non-PGDT modules and turn the power off and on. If this has solved the error: • Connect each non-PGDT module in turn and turn the power off and on each time to see which module causes the problem. If this does not solve the error, the power module may be defect.
PM Memory Error	-	This is a specific error for the Power Module • Check all cables and connections. • Re-program the control system. Use the R-Net PC programmer to program the most current specific program for wheelchair or the manufacturers original programming file. If this does not solve the error, the power module may be defect.

Trip Text	Trip code	Description
Gone to Sleep	-	The control system has been left inactive for a longer period of time than the time indicated by the Sleep Timer. An entry is made in the log each time this occurs. The control system "wake up" again when the joystick or a button is used.
Charging	-	The control system detects that a charger is connected to Inhibit 1 or to in Inhibit 3. The *Battery charger* screen is shown during charger connection. An entry is made in the system log each time this occurs. If the On-Board charger is used: • Disconnect the charger from the AC supply. If an Off-Board charger is used: • Disconnect the charger from the wheelchair. If this error is still present when the charger is disconnect, the joystick module may be defect.

7.5. Diagnostics and troubleshooting for VR2 controls

WARNING!
Remove both fuses from the batteries before you change any cables, fuses and/or modules. This way the power way is disconnected from the wheelchair.

NOTICE!
For more detailed information about VR2 Controllers, specific manuals can be downloaded from the website: www.pgdt.com.

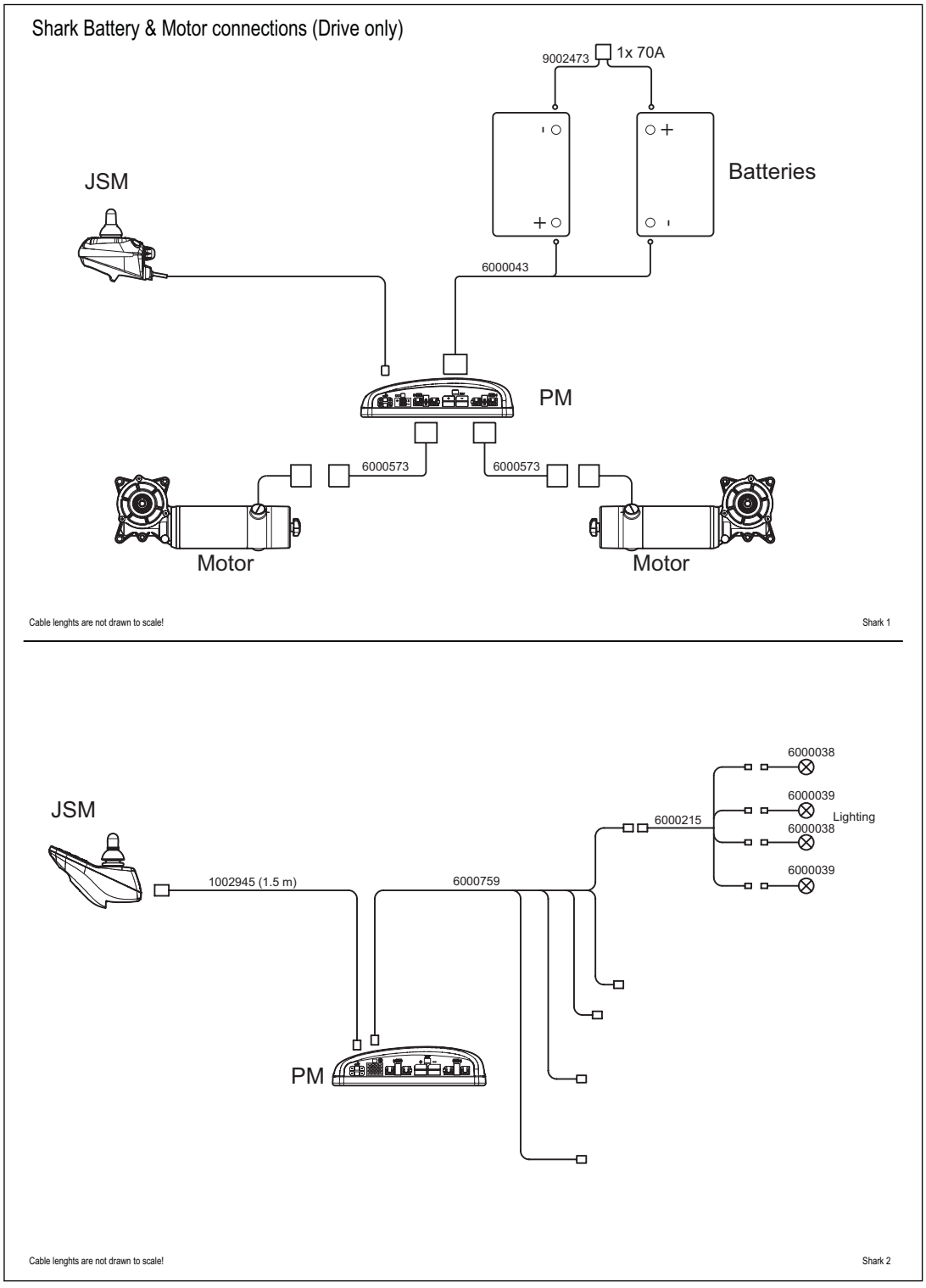
The number of LEDs on the battery indicator indicates the type of fault.

Fault signal/problem	Cause	Solution
1 LED	The battery needs charging or there is a bad connection to the battery.	Check the battery connections and recharge the battery.
2 LEDs	The left-hand motor (m1) connection is not good.	Check the connection and the cabling.
3 LEDs	The left-hand motor (m1) has a short circuit connection to the battery.	Contract your supplier.
4 LEDs	The right-hand motor (m2) connection is not good.	Check the connection and the cabling.
5 LEDs	The right-hand motor (m2) has a short circuit connection to the battery.	Contact your supplier.
6 LEDs	An extenal signal prevents the wheelchair from driving.	The extact cause depends on the type of wheelchair, one possibility is that the battery charger is still connected.
7 LEDs	Joystick fault.	Make sure that the joystick is in the center position and re-try to switch on the system.
8 LEDs	Control system fault.	Check all connections and cables.
9 LEDs	The parking brakes have a bad connection.	Check the connections of the parking brake and of the motor.
10 LEDs	An excessive voltage has been applied to the control system. This is usually cause by a poor battery connection.	Check the battery connections.
7 LEDs + Speed indicator	Communication fault.	Check the connection and the condition of the joystick cable.
8 LEDs + Actuator indicator	Actuator trip	If more that one actuator is installed, check which one in not working correctly. Check the actuator cabling.
Wheelchair moves slow or slugglish	Battery in poor condition	Check the battery
	Setting for maximum speed is too low.	Adjust the setting for maxium speed.

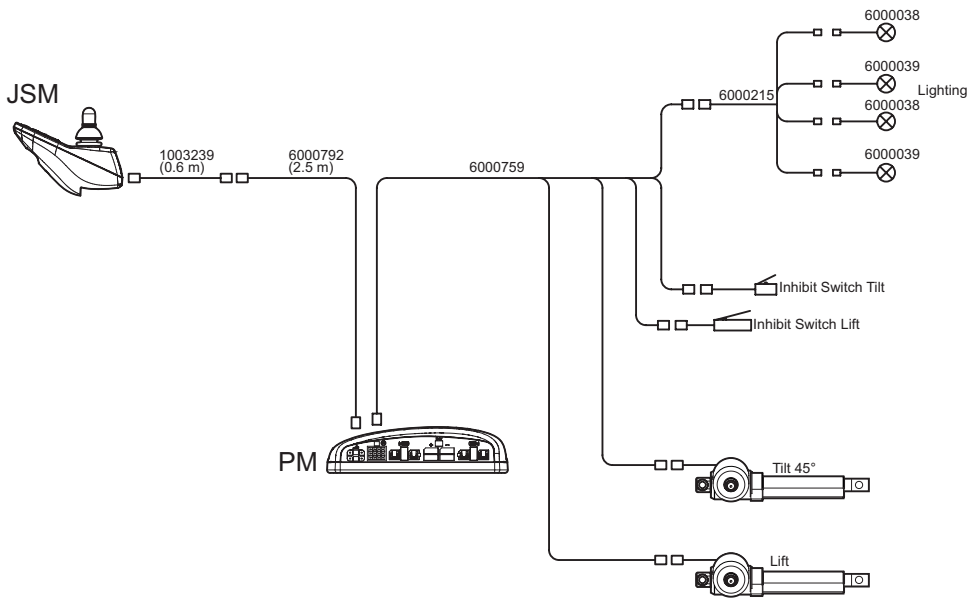
Fault signal/problem	Cause	Solution
Speed / profile indicator ripples up and down	The controls system is locked.	Unlock the controls system (see the user manual of the controls system).
Speed / profile indicator flashes	The speed of the wheelchair is being limited for safety reasons.	The extact cause depends on the type of wheelchair, most common cause is that the seat is in the elevated position.
Actuator LED flashes	The actuator may be inhibited in one or both directions to prevent a unstable setting of the wheelchair. Most likely the user has put an other setting (like: lift) in a maximum position.	Put the other settings in a neutral position.

8. Cable and module schemes

8.1. Shark controls



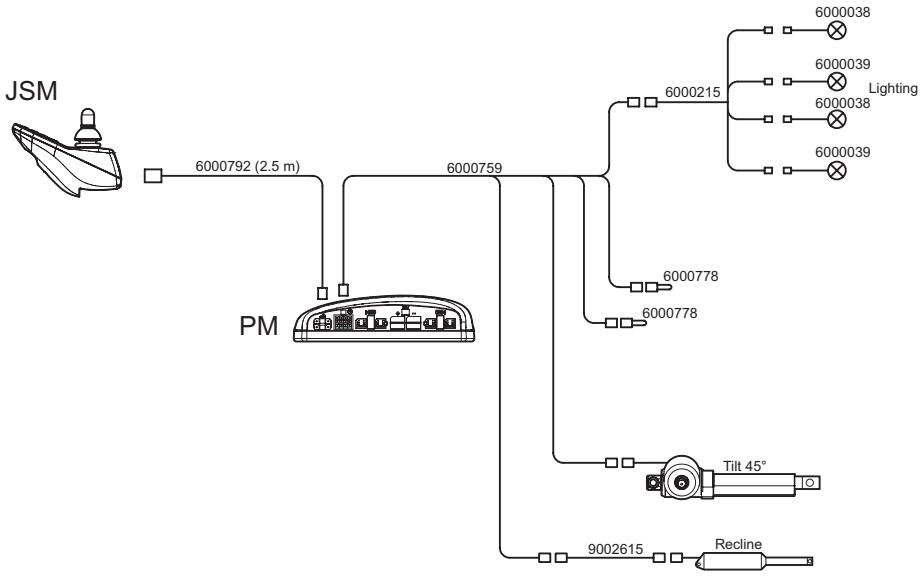
Shark Qlass Tilt45 & Lift (Lights optional)



Cable lenghts are not drawn to scale!

Shark 3

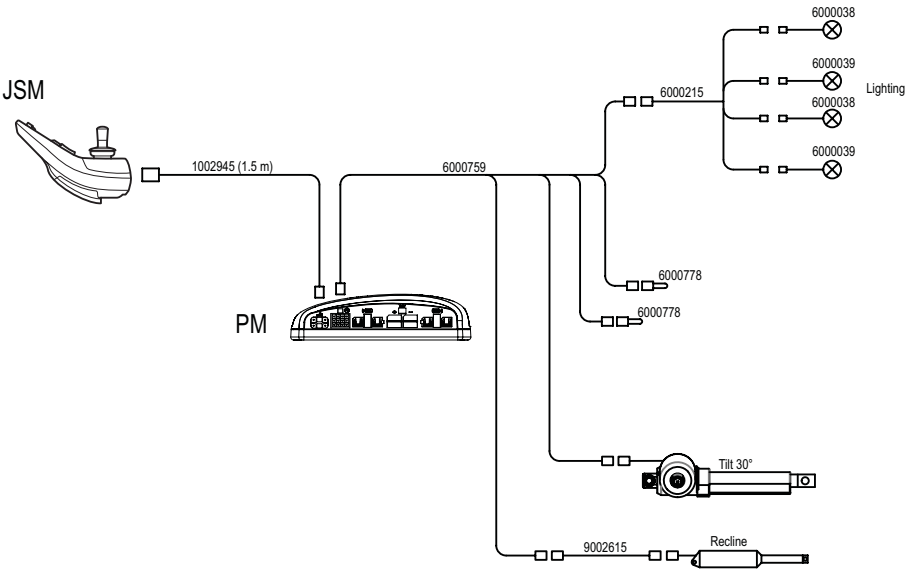
Shark Qlass Tilt45 & Recline (Lights optional)



Cable lenghts are not drawn to scale!

Shark 4

Shark EQlass Tilt30° & Recline (Lights optional)

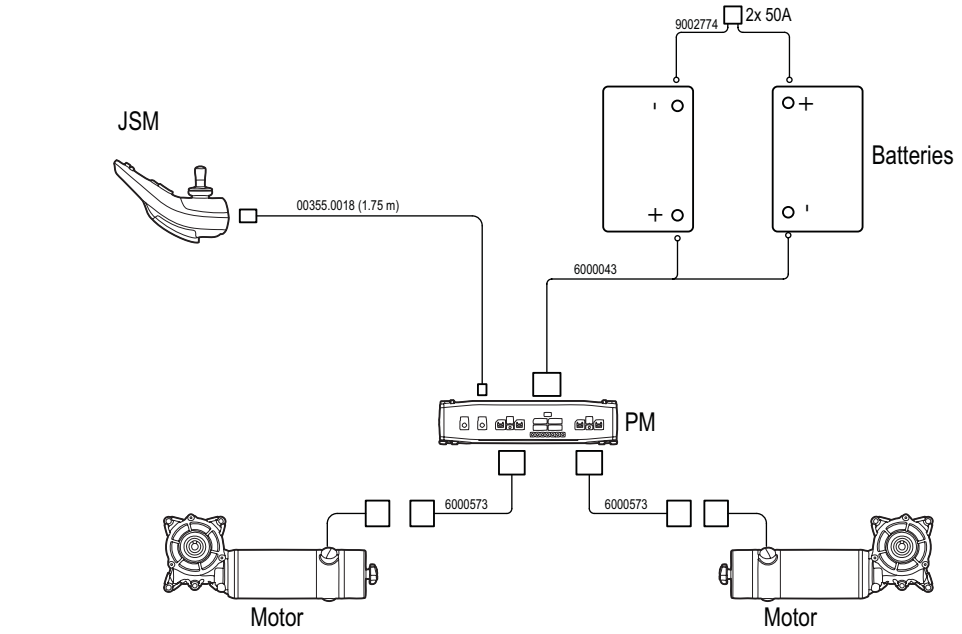


Cable lenghts are not drawn to scale!

Shark 5

8.2. DX2 controls

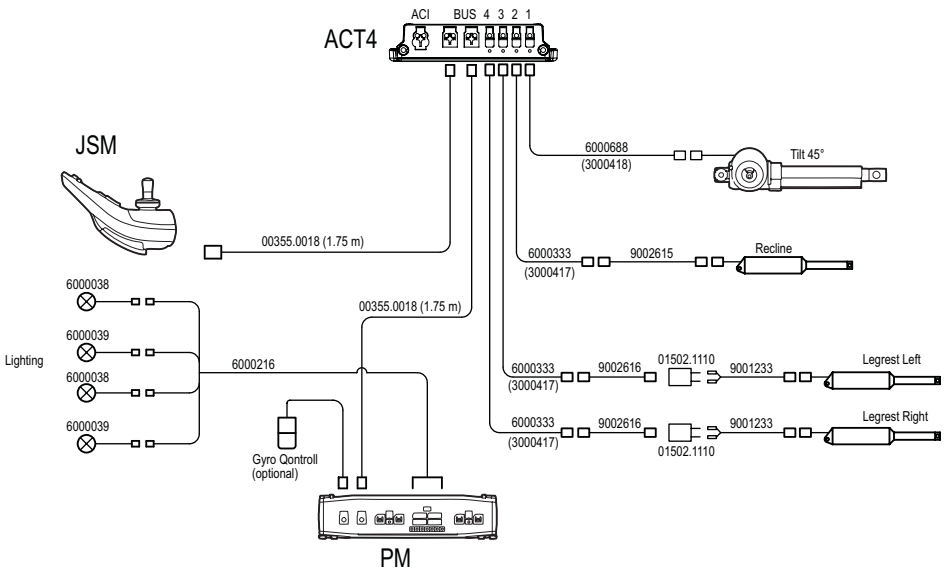
DX2 Battery & Motor connections (Drive only)



Cable lenghts are not drawn to scale!

DX2 1

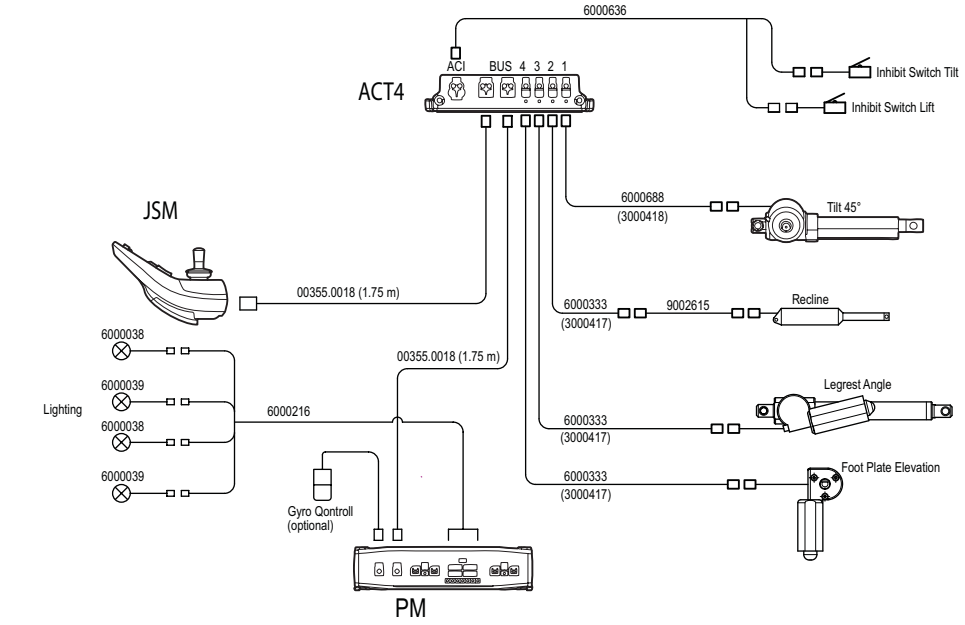
DX2 Tilt45, Recline, Legrests (Lights, Indicators & Gyro optional)
REM550/REM420



Cable lenghts are not drawn to scale!

DX2 2

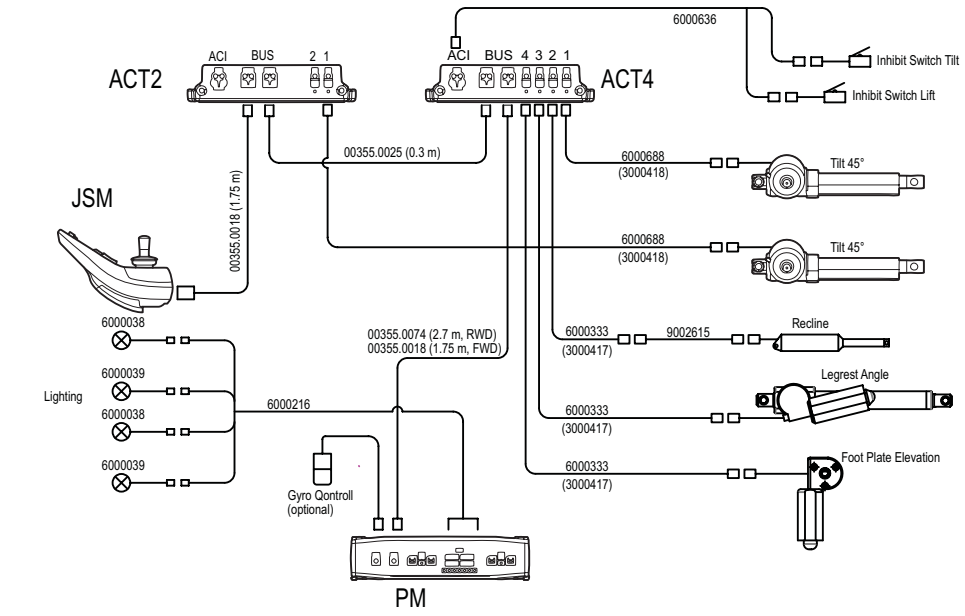
DX2 Tilt45, Recline, Powered Central Legrest (Lights, Indicators & Gyro optional)
REM550/REM420



Cable lenghts are not drawn to scale!

DX2 3

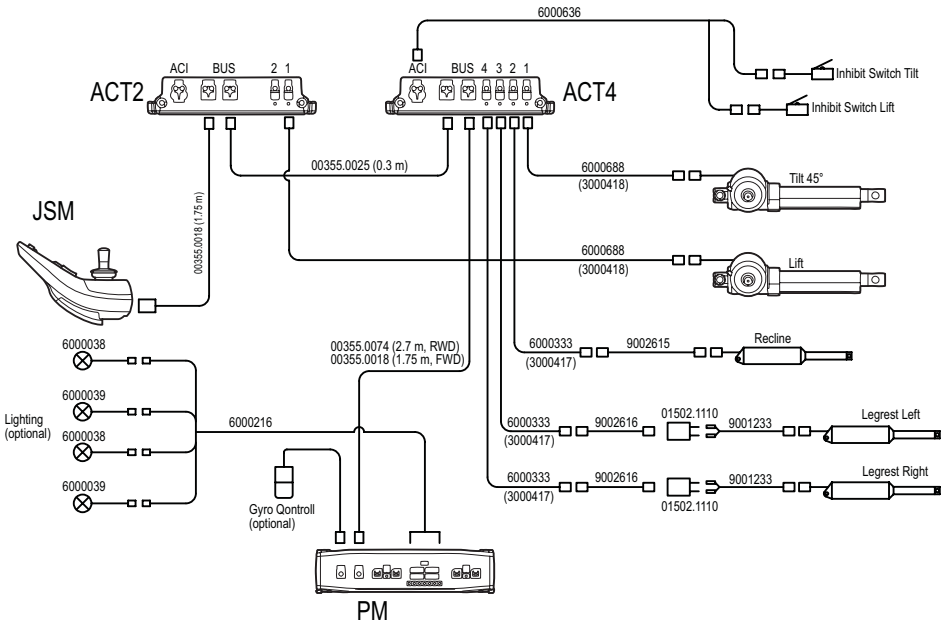
DX2 Tilt45, Recline, Powered Central Legrest, Lift (Lights, Indicators & Gyro optional)
REM550 only



Cable lenghts are not drawn to scale!

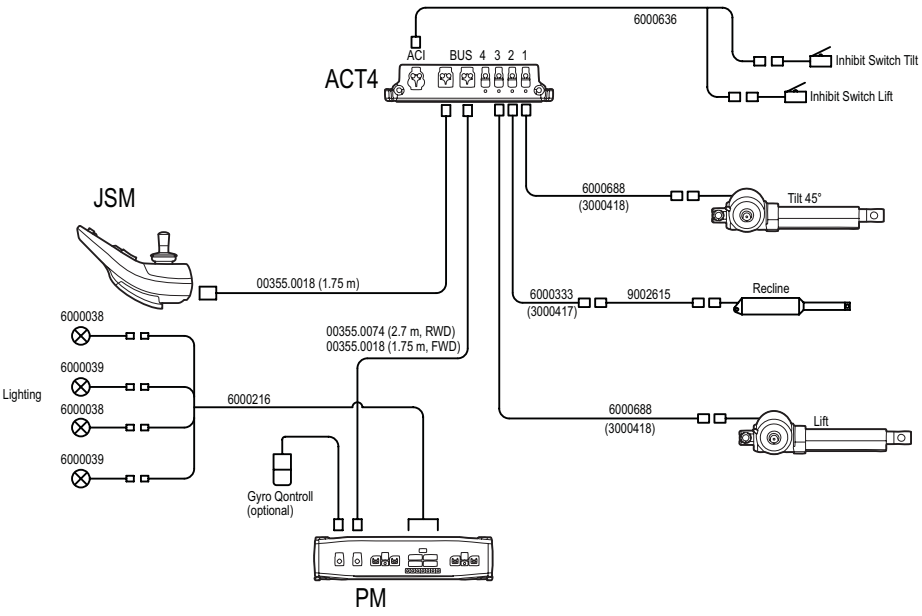
DX2 4

DX2 Tilt45, Recline, Legrests, Lift (Lights, Indicators & Gyro optional)
REM550 only



DX2 5

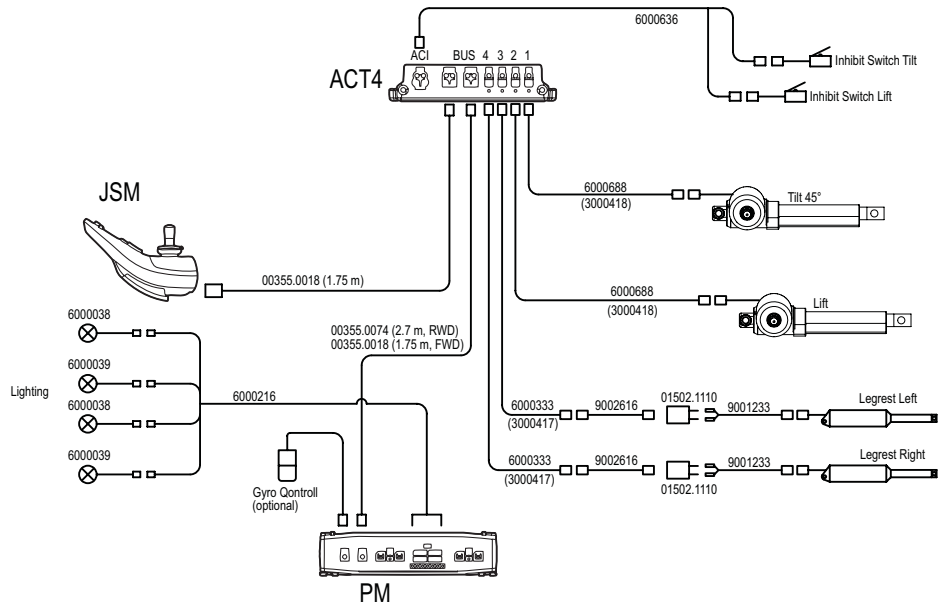
DX2 Tilt45, Recline, Lift (Lights, Indicators & Gyro optional)
REM550/REM420



Cable lenghts are not drawn to scale!

DX2 6

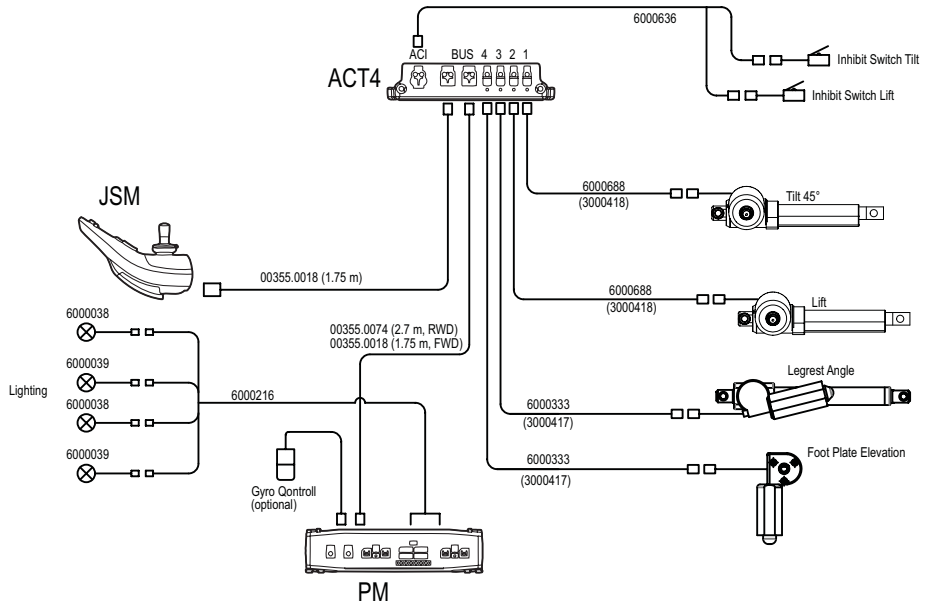
DX2 Tilt45, Legrests, Lift (Lights, Indicators & Gyro optional)
REM550/REM420



Cable lenghts are not drawn to scale!

DX2 7

DX2 Tilt45, Powered Central legrest, Lift (Lights, Indicators & Gyro optional)
REM550/REM420

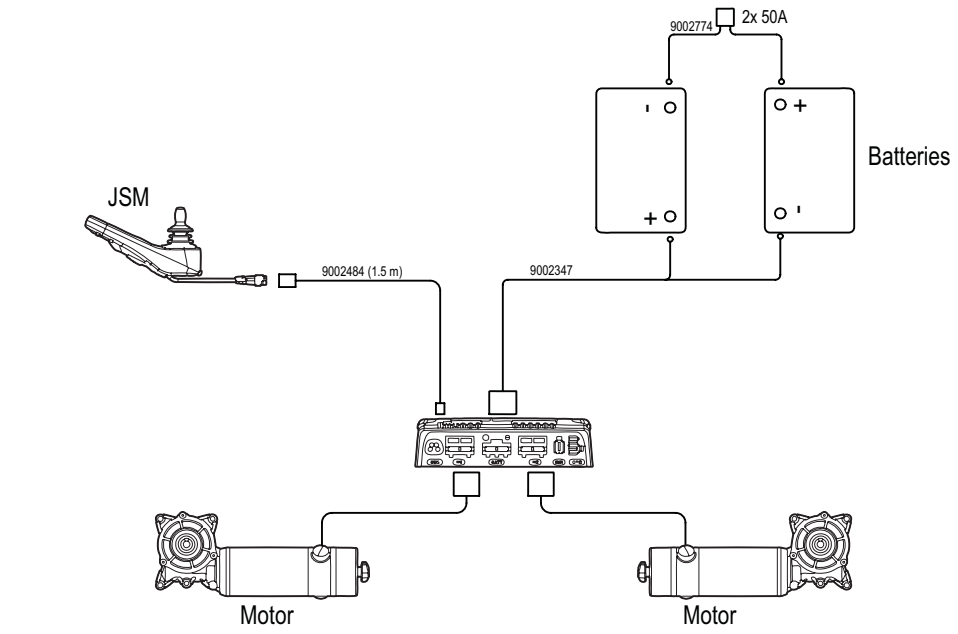


Cable lenghts are not drawn to scale!

DX2 8

8.3. R-Net controls

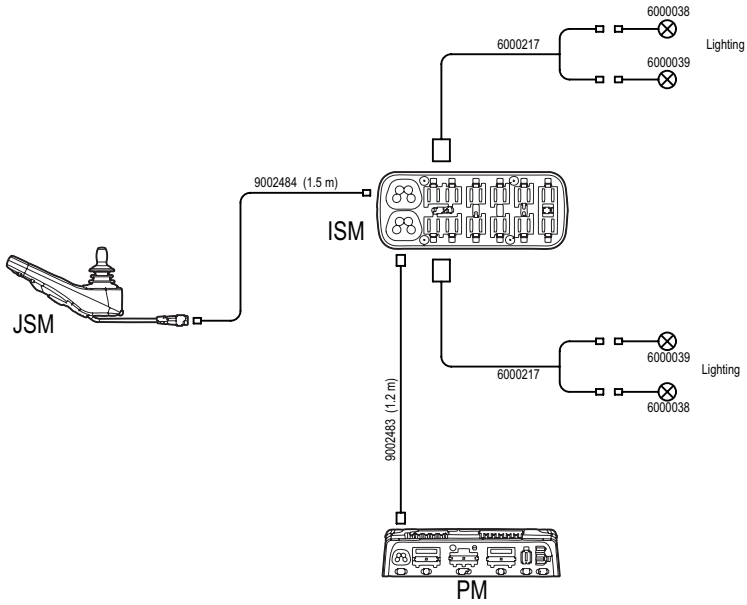
R-Net Battery & Motor connections (Drive only)



Cable lenghts are not drawn to scale!

R-Net 1

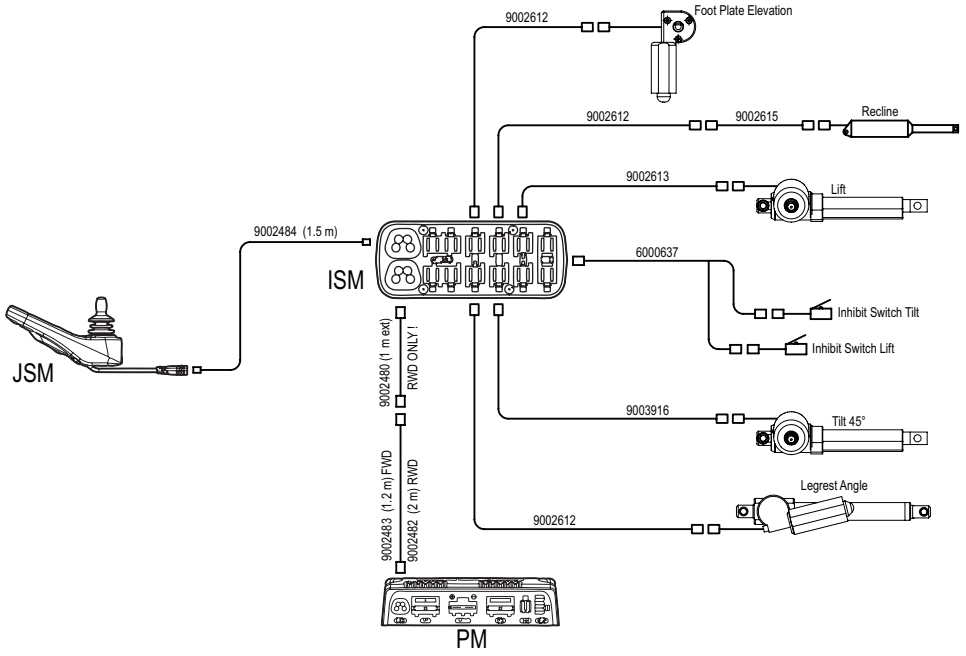
R-Net Drive & Lights



Cable lenghts are not drawn to scale!

R-Net 2

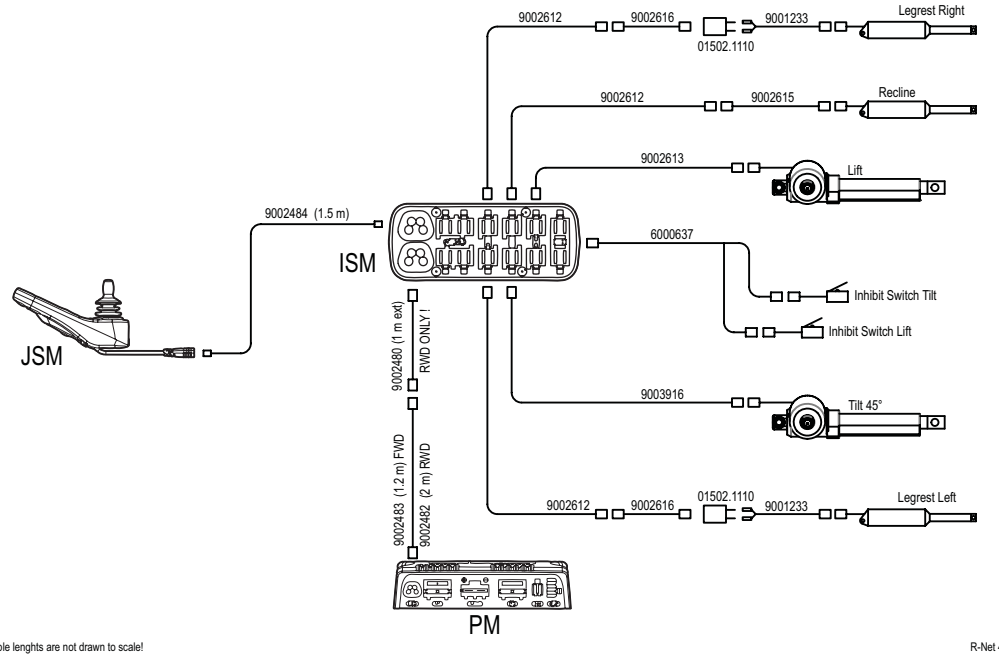
R-Net Tilt45, Recline, Powered Central Legrest, Lift (lights can be optional)



Cable lenghts are not drawn to scale!

R-Net 3

R-Net Tilt45, Recline, Legrests, Lift (Lights can be optional)

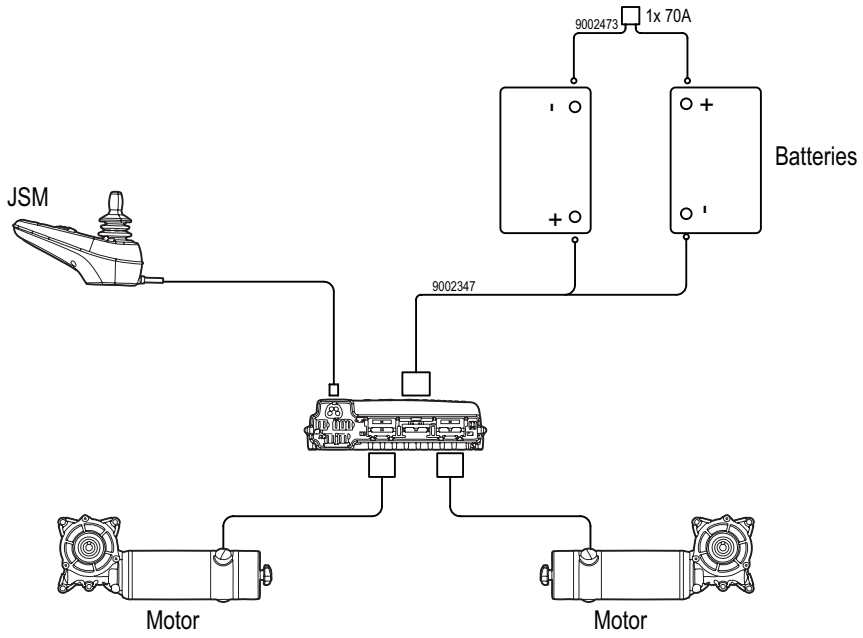


Cable lenghts are not drawn to scale!

R-Net 4

8.4. VR2 controls

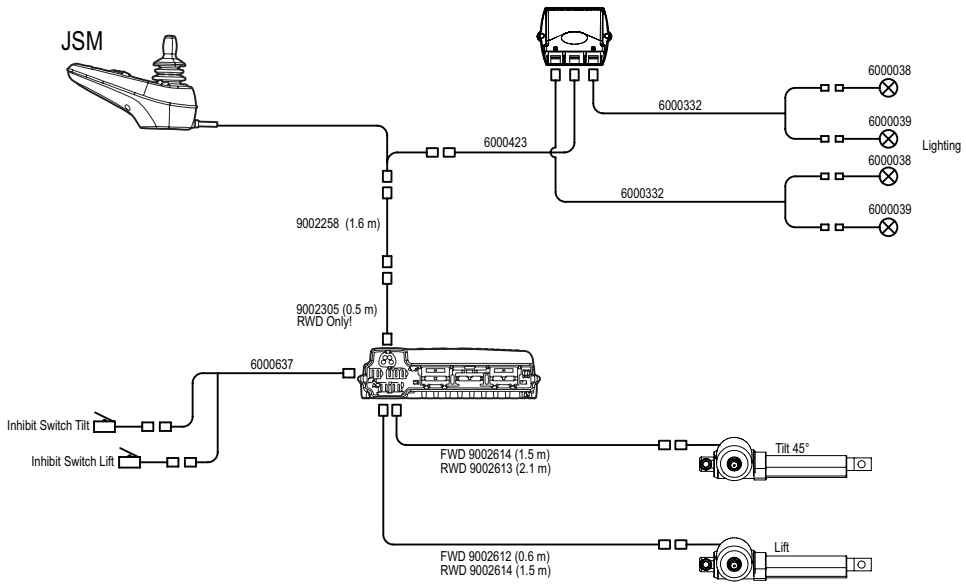
VR2 Battery & Motor connections (Drive only)



Cable lenghts are not drawn to scale!

VR2 1

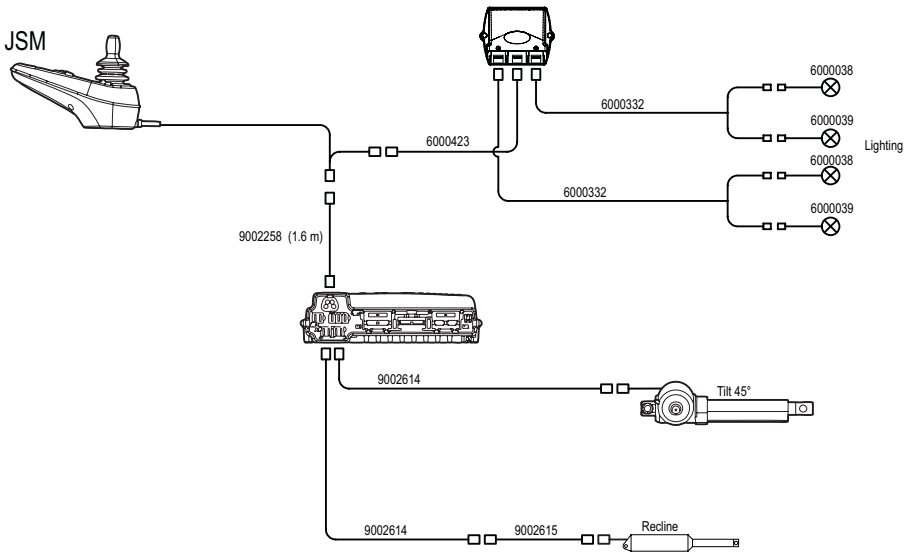
VR2 Tilt45 & Lift (Lights optional)



Cable lenghts are not drawn to scale!

VR2 2

VR2 Tilt45 & Recline (Lights optional)



Cable lenghts are not drawn to scale!

VR2 3

9. Version history

Version	Release date	Changes
V1.0	Dec. 5th 2013	First released version.
V2.0	Jan. 1st 2015	New company name.